

Day 4A

Asymptotic Theory

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*Based on A. Colin Cameron and Pravin K. Trivedi (2009, 2010),
Microeconometrics using Stata (MUS), Stata Press.
and A. Colin Cameron and Pravin K. Trivedi (2005),
Microeconometrics: Methods and Applications (MMA), C.U.P.*

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1. Introduction

- Consider sample mean $\bar{y} = \frac{1}{N} \sum_{i=1}^N y_i$ as an estimator of the population mean μ
 - ▶ asymptotic theory gives properties of \bar{y} as $N \rightarrow \infty$.
- Make assumptions about the **data generating process** (dgp)
 - ▶ $y_i \sim (\mu, \sigma^2)$ i.i.d. (independent and identically distributed)
 - ▶ $\implies \bar{y} \sim (\mu, \sigma^2/N)$.

- The distribution of \bar{y} has all mass at the mean of μ as $N \rightarrow \infty$
 - ▶ Intuition: $V[\bar{y}] = E[(\bar{y} - \mu)^2] = \sigma^2 / N \rightarrow 0$.
 - ▶ Formally \bar{y} **converges in probability** (defined below) to μ
 - ▶ This is denoted $\bar{y} \xrightarrow{P} \mu$ or $\text{plim } \bar{y} = \mu$.
 - ▶ Then \bar{y} is **consistent** for μ .
 - ▶ The proof uses a **law of large numbers** (defined below) for an average.

- Statistical inference based on \bar{y} with $N \rightarrow \infty$ requires scaling \bar{y} up
 - ▶ Use standardized statistic $z = \frac{\bar{y} - E[\bar{y}]}{\sqrt{V[\bar{y}]}} = \frac{\bar{y} - \mu}{\sigma/\sqrt{N}}$.
 - ▶ $z \sim (0, 1)$, so z may have a nondegenerate distribution.
 - ▶ A **central limit theorem** (defined below) proves $z \sim \mathcal{N}(0, 1)$ as $N \rightarrow \infty$.
 - ▶ Formally z **converges in distribution** (\xrightarrow{d} , defined below) to $\mathcal{N}[0, 1]$.
 - ▶ Equivalently $\sqrt{N}(\bar{y} - \mu) \xrightarrow{d} \mathcal{N}[0, \sigma^2]$.
 - ▶ Note: \bar{y} has been scaled up by the multiple \sqrt{N} .

- For simplicity, the formal result $\sqrt{N}(\bar{y} - \mu) \xrightarrow{d} \mathcal{N}[0, \sigma^2]$ is often re-expressed in terms of \bar{y}
 - ▶ $\bar{y} \stackrel{a}{\sim} \mathcal{N}[0, \sigma^2 / N]$
 - ▶ $\stackrel{a}{\sim}$ means “is asymptotically distributed as”
 - ▶ this means N is large enough that the normal is a good approximation
 - ▶ but N is not so large that $\sigma^2 / N = 0$.

Outline

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2. Sequences of random variables

- Recall a sequence of real numbers
 - ▶ e.g. $a_N = 2 + \frac{3}{N}$
- What happens as $N \rightarrow \infty$?
 - ▶ mathematical convergence (or divergence)
- A sequence of nonstochastic real numbers $\{a_N\}$ *converges* to a if for any $\varepsilon > 0$, there exists $N^* = N^*(\varepsilon)$ such that for all $N > N^*$,

$$|a_N - a| < \varepsilon.$$

- ▶ e.g. $a_N = 2 + 3/N \rightarrow 2$ since
 $|a_N - a| = |2 + 3/N - 2| = |3/N| < \varepsilon$ for all $N > N^* = 3/\varepsilon$.

- We instead consider a sequence of random variables b_N .
 - ▶ e.g. $b_N = \frac{1}{N} \sum_{i=1}^N x_i^2$
 - ▶ e.g. $b_N = \frac{1}{N} \sum_{i=1}^N x_i u_i$
 - ▶ e.g. $b_N = \hat{\beta} = \left(\frac{1}{N} \sum_{i=1}^N x_i^2 \right)^{-1} \frac{1}{N} \sum_{i=1}^N x_i u_i$
- What happens as $N \rightarrow \infty$?
 - ▶ $|b_N - b|$ may exceed ε due to randomness, so $b_N \not\rightarrow b$ exactly
 - ▶ instead use convergence in probability.

3. Convergence in probability and consistency

- Informal definition: The sequence $\{b_N\}$ *converges in probability* to b if for any $\varepsilon > 0$

$$\lim_{N \rightarrow \infty} \Pr[|b_N - b| < \varepsilon] = 1.$$

- Formal definition: A sequence of random variables $\{b_N\}$ *converges in probability* to b if for any $\varepsilon > 0$ and $\delta > 0$, there exists $N^* = N^*(\varepsilon, \delta)$ such that for all $N > N^*$,

$$\Pr[|b_N - b| < \varepsilon] > 1 - \delta.$$

- We write $\text{plim } b_N = b$ or $b_N \xrightarrow{P} b$
 - ▶ the limit b may be a constant or a random variable.

Consistency

- Suppose the sequence b_N is an estimator, say $b_N = \hat{\beta}$.
 - ▶ If $\hat{\beta} \xrightarrow{P} \beta$, a constant, then we say $\hat{\beta}$ is *consistent* for β .
- A simple consistency proof uses *convergence in mean square*
 - ▶ that is $\lim_{N \rightarrow \infty} E[(b_N - \beta)^2] = 0$
 - ▶ \xrightarrow{ms} implies convergence in probability.
- Suppose $\hat{\beta}$ is used to estimate β
 - ▶ $E[(\hat{\beta} - \beta)^2] = V[\hat{\beta}] + (\text{bias}[\hat{\beta}])^2$ as $\text{MSE} = \text{variance} + \text{bias}^2$
 - ▶ so $\hat{\beta} \xrightarrow{ms} \beta$ if $V[\hat{\beta}] \rightarrow 0$ and $\text{bias}[\hat{\beta}] \rightarrow 0$ as $N \rightarrow \infty$
 - ▶ it follows that $\hat{\beta} \xrightarrow{P} \beta$ if the variance and bias go to zero as $N \rightarrow \infty$.
- We use the weaker convergence in probability as $\hat{\beta} \xrightarrow{P} \beta$ is possible even if the mean and variance of $\hat{\beta}$ do not exist.

4. Law of large numbers

- Easy way to get probability limit when b_N is an average

$$b_N = \bar{X}_N = \frac{1}{N} \sum_{i=1}^N X_i.$$

- ▶ X_i here is general notation for a random variable. e.g. $X_i = x_i u_i$.

- *Weak Law of Large Numbers (WLLN)*:

Specifies conditions on the individual terms X_i in \bar{X}_N under which

$$(\bar{X}_N - E[\bar{X}_N]) \xrightarrow{P} 0.$$

- *Khinchine's Theorem (WLLN)*:

Let $\{X_i\}$ be i.i.d. (independent and identically distributed).

If and only if $E[X_i] = \mu$ exists, then $(\bar{X}_N - \mu) \xrightarrow{P} 0$.

- Other LLN's are Kolmogorov and, for i.n.i.d. data, Markov
 - ▶ these are given later.
- If a LLN can be applied then

$$\begin{aligned}
 \text{plim } \bar{X}_N &= \lim E[\bar{X}_N] && \text{in general} \\
 &= \lim N^{-1} \sum_{i=1}^N E[X_i] && \text{equivalently} \\
 &= \mu && \text{if } X_j \text{ i.i.d.}
 \end{aligned}$$

5. Convergence in distribution

- b_N has (unknown) cumulative distribution function (cdf) F_N . Like any other function, F_N may have a limit function.
- *Convergence in Distribution:*
A sequence of random variables $\{b_N\}$ *converges in distribution* to a random variable b if

$$\lim_{N \rightarrow \infty} F_N = F, \text{ where } F \text{ is the c.d.f. of } b$$

at every continuity point of F , where convergence is in the usual mathematical sense.

- We write $b_N \xrightarrow{d} b$, and call F the *limit distribution* of $\{b_N\}$.
- Basically F_N is very complicated and F is simple like $\mathcal{N}[0, 1]$.

6. Central limit theorems

- Easy way to get limit distribution when b_N is an average \bar{X}_N .
- \bar{X}_N has a degenerate limit distribution with all mass at one point since $\bar{X}_N \xrightarrow{p} \lim E[\bar{X}_N]$ by a LLN.
- So rescale \bar{X}_N to standardized variate

$$b_N = Z_N = \frac{\bar{X}_N - E[\bar{X}_N]}{\sqrt{V[\bar{X}_N]}} \sim [0, 1].$$

- *Central Limit Theorem (CLT)*:

A CLT specifies the conditions on the individual terms X_i in \bar{X}_N under which

$$Z_N \xrightarrow{d} \mathcal{N}[0, 1].$$

- *Lindeberg-Levy CLT*:

Let $\{X_i\}$ be i.i.d. with $E[X_i] = \mu$ and $V[X_i] = \sigma^2$.

Then $Z_N = \sqrt{N}(\bar{X}_N - \mu) / \sigma \xrightarrow{d} \mathcal{N}[0, 1]$.

- Note that

$$\begin{aligned}
 Z_N &= (\bar{X}_N - \mathbf{E}[\bar{X}_N]) / \sqrt{\mathbf{V}[\bar{X}_N]} && \text{in general} \\
 &= \sum_{i=1}^N (X_i - \mathbf{E}[X_i]) / \sqrt{\sum_{i=1}^N \mathbf{V}[X_i]} && \text{if } X_i \text{ independent over } i \\
 &= \sqrt{N}(\bar{X}_N - \mu) / \sigma && \text{if } X_i \text{ i.i.d.}
 \end{aligned}$$

- The last expression can be rewritten as

$$\frac{\bar{X}_N - \mu}{\sigma / \sqrt{N}} \xrightarrow{d} \mathcal{N}[0, 1].$$

- It follows that $\sqrt{N}(\bar{X}_N - \mu) \xrightarrow{d} \mathcal{N}[0, \sigma^2]$.
- More generally we often find $\sqrt{N}(\hat{\beta} - \beta) \xrightarrow{d} \mathcal{N}[0, V]$.
 - Scale consistent $\hat{\beta}$ up by \sqrt{N} to get a limit distribution.

Multivariate central limit theorem

- Consider vector $\bar{\mathbf{X}}_N$ with mean $\boldsymbol{\mu}_N$ and variance \mathbf{V}_N

$$\bar{\mathbf{X}}_N \sim [\boldsymbol{\mu}_N, \mathbf{V}_N].$$

- Rescale $\bar{\mathbf{X}}_N$ to standardized variate

$$\mathbf{z}_N = \mathbf{V}_N^{-1/2}(\bar{\mathbf{X}}_N - \boldsymbol{\mu}_N) \sim [\mathbf{0}, \mathbf{I}].$$

- *Central Limit Theorem (CLT)*:

A CLT specifies the conditions on the individual terms \mathbf{X}_i in $\bar{\mathbf{X}}_N$ under which

$$\mathbf{z}_N \xrightarrow{d} \mathcal{N}[\mathbf{0}, \mathbf{I}].$$

- Often $\lim N\mathbf{V}_N$ is finite nonzero
 - ▶ for example if $\mathbf{X}_i \sim (\boldsymbol{\mu}, \Sigma)$ then $\mathbf{V}_N = V[\bar{\mathbf{X}}_N] = N^{-1}\Sigma$, so $N\mathbf{V}_N = \Sigma$.
- Then $\mathbf{V}_N^{-1/2}(\bar{\mathbf{X}}_N - \boldsymbol{\mu}_N) \xrightarrow{d} \mathcal{N}[\mathbf{0}, \mathbf{I}]$ implies

$$\sqrt{N}(\bar{\mathbf{X}}_N - \boldsymbol{\mu}_N) \xrightarrow{d} \mathcal{N}[\mathbf{0}, \lim N^{-1}\mathbf{V}_N]$$

- ▶ scaling the average $\bar{\mathbf{X}}_N$ by a multiple \sqrt{N} gives a limit distribution with a finite nonzero variance.

7. Some Key Results

- *Probability Continuity and Continuous Mapping Theorems*

Let \mathbf{b}_N be a vector of random variables, and $g(\cdot)$ be a continuous real-valued function. Then

$$\begin{aligned} \mathbf{b}_N \xrightarrow{P} \mathbf{b}, \text{ a constant} &\Rightarrow g(\mathbf{b}_N) \xrightarrow{P} g(\mathbf{b}) && \text{Probability Continuity} \\ \mathbf{b}_N \xrightarrow{d} \mathbf{b} &\Rightarrow g(\mathbf{b}_N) \xrightarrow{d} g(\mathbf{b}) && \text{Continuous Mapping} \end{aligned}$$

- *Transformation Theorem:*

If $a_N \xrightarrow{d} a$ (a random variable) and $b_N \xrightarrow{P} b$ (a constant), then

$$\begin{aligned} (i) \quad a_N + b_N &\xrightarrow{d} a + b \\ (ii) \quad a_N b_N &\xrightarrow{d} ab \\ (iii) \quad a_N / b_N &\xrightarrow{d} a/b, \quad \text{provided } \Pr[b = 0] = 0. \end{aligned}$$

- ▶ We use especially a matrix version of (ii).

- *Product Limit Normal Rule:*

For vector \mathbf{a}_N and matrix \mathbf{H}_N , if

$$\mathbf{a}_N \xrightarrow{d} \mathcal{N}[\boldsymbol{\mu}, \mathbf{A}]$$

$$\mathbf{H}_N \xrightarrow{p} \mathbf{H}, \quad \text{where } \mathbf{H} \text{ is positive definite}$$

then

$$\mathbf{H}_N \mathbf{a}_N \xrightarrow{d} \mathcal{N}[\mathbf{H}\boldsymbol{\mu}, \mathbf{H}\mathbf{A}\mathbf{H}'].$$

- Leading example is OLS:

$$\begin{aligned} \sqrt{N}(\hat{\boldsymbol{\beta}} - \boldsymbol{\beta}_0) &= \left(\frac{1}{N}\mathbf{X}'\mathbf{X}\right)^{-1} \times \frac{1}{\sqrt{N}}(\mathbf{X}'\mathbf{u}) \\ &\xrightarrow{d} \mathcal{N}[\mathbf{A}^{-1} \times \mathbf{0}, \mathbf{A}^{-1}\mathbf{B}\mathbf{A}^{-1}']. \end{aligned}$$


```

. * Central limit theorem
. * Write program to obtain sample mean for one sample of size numobs (= 30)
. program onesample, rclass
1.     args numobs
2.     drop _all
3.     quietly set obs `numobs'
4.     generate x = runiform()
5.     summarize x
6.     return scalar meanforonesample = r(mean)
7. end

. * Run this program 10,000 times to get 10,000 sample means
. quietly simulate xbar = r(meanforonesample), seed(10101) reps(10000) nodots: ///
>     onesample 30

. * Summarize the 10,000 sample means and draw histogram
. summarize xbar

```

Variable	Obs	Mean	Std. Dev.	Min	Max
xbar	10000	.4995835	.0533809	.3008736	.6990562

```

. histogram xbar, normal xtitle("xbar from many samples")
(bin=40, start=.30087364, width=.00995456)

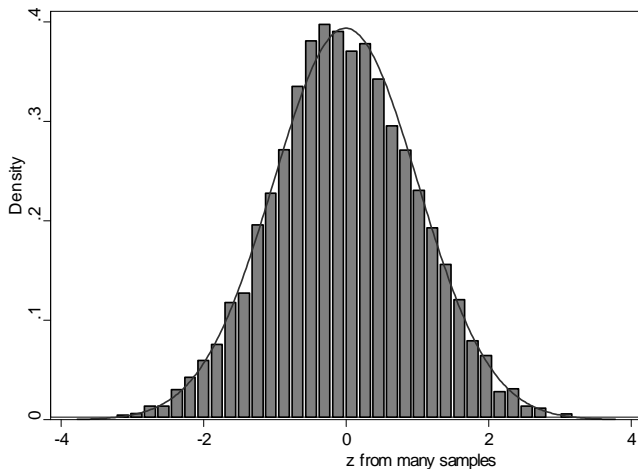
```

For $S = 10,000$ simulations each with sample size $N = 30$

$\bar{x}_1, \bar{x}_2, \dots, \bar{x}_{10000}$ has distribution with mean 0.4996 close to $\mu = 0.500$

and standard deviation 0.0534, close to $\sigma/\sqrt{N} = \sqrt{1/12}/\sqrt{30} = 0.0527$.

$z = (\bar{x} - \mu)/(\sigma/\sqrt{N}) = (\bar{x} - 0.5)/(\sqrt{1/12}/\sqrt{30}) = (\bar{x} - 0.5)/0.0527$.
Histogram and kernel density estimate for $z_1, z_2, \dots, z_{10000}$.



This is standard normal, as predicted by the CLT.

9. Appendix: Some Further Asymptotic Results

- Alternative modes of convergence of b_N to b
 - ▶ *Mean square*: $\lim_{N \rightarrow \infty} E[(b_N - b)^2] = 0$.
 - ▶ *Chebychev's inequality*: $\Pr[(Z - \mu)^2 > k] \leq \sigma^2/k$, for any $k > 0$.
 - ▶ *Almost sure*: $\Pr\{\omega \mid \lim b_N(\omega) = b(\omega)\} = 1$.
 - ▶ These imply convergence in probability.
- Consequences:
 - ▶ $b_N \xrightarrow{p} b$ implies $b_N \xrightarrow{d} b$.
 - ▶ The reverse is generally not true, unless b is a constant.
 - ▶ For vector r.v.'s define F_N and F to be cdf's of vectors \mathbf{b}_N and \mathbf{b} .

- *Strong Law of Large Numbers (LLN):*

- ▶ The convergence is instead almost surely (\xrightarrow{as}).

- *Kolmogorov SLLN:*

Let $\{X_i\}$ be i.i.d. If and only if $E[X_i] = \mu$ exists and $E[|X_i|] < \infty$, then $(\bar{X}_N - E[\bar{X}_N]) \xrightarrow{as} 0$.

- ▶ Compared to Khinchine's Theorem \xrightarrow{as} requires $E[|X_i|] < \infty$.

- *Markov SLLN:*

Let $\{X_i\}$ be i.n.i.d. with $E[X_i] = \mu_i$.

If $\sum_{i=1}^{\infty} (E[|X_i - \mu_i|^{1+\delta}] / i^{1+\delta}) < \infty$, for some $\delta > 0$, then

$(\bar{X}_N - E[\bar{X}_N]) \xrightarrow{as} 0$.

- ▶ Relaxes i.i.d. assumption at expense of requiring existence of $(1 + \delta)^{th}$ absolute moment.
- ▶ Easiest to set $\delta = 1$, so need variance.

- *Liapounov CLT:*

Let $\{X_i\}$ be independent with $E[X_i] = \mu_i$ and $V[X_i] = \sigma_i^2$.

If $\lim \left(\sum_{i=1}^N E[|X_i - \mu_i|^{2+\delta}] \right) / \left(\sum_{i=1}^N \sigma_i^2 \right)^{(2+\delta)/2} = 0$, for some choice of $\delta > 0$, then $Z_N \xrightarrow{d} \mathcal{N}[0, 1]$.

- ▶ The Liapounov CLT relaxes i.i.d. assumption but needs existence of $(2 + \delta)^{th}$ absolute moment.

- *Cramer-Wold Device:*

If $\lambda' \mathbf{b}_N \xrightarrow{d} \mathcal{N}[\cdot, \cdot]$ for all $\lambda \neq \mathbf{0}$ then $\mathbf{b}_N \xrightarrow{d} \mathcal{N}[\cdot, \cdot]$.

- ▶ So prove a multivariate CLT by proving a scalar CLT for $\lambda' \mathbf{b}_N$.

9. Appendix: Sampling schemes

- Simple Random Sampling (SRS)
 - ▶ Randomly draw (y_i, x_i) from the population with equal probabilities.
 - ▶ Then x_i i.i.d. So $x_i u_i$ i.i.d. (if errors u_i are i.i.d.), and x_i^2 i.i.d.
 - ▶ Can use Khinchine's LLN and Lindeberg-Levy CLT.
- Fixed regressors
 - ▶ Experiment where x_i are fixed and we observe the resulting random y_i .
 - ▶ Then x_i fixed, u_i i.i.d. implies $x_i u_i$ i.n.i.d. and x_i^2 nonstochastic.
 - ▶ Need to use Markov LLN and Liapounov CLT.
- Exogenous Stratified Sampling
 - ▶ Oversample some values of x and undersample others.
 - ▶ Then x_i i.n.i.d., so $x_i u_i$ i.n.i.d. and x_i^2 i.n.i.d.
 - ▶ Need to use Markov LLN and Liapounov CLT.

- These three different sampling schemes ultimately lead to similar asymptotic results.
- Microeconometrics often use survey data obtained by stratified sampling.
- The simplest results assume simple random sampling.
- Big problems arise if the stratified sampling is Instead
Endogenous Stratified Sampling
 - ▶ Oversample some values of y and undersample others.
 - ▶ Estimators can be inconsistent.
 - ▶ Leading examples are Tobit and selection models.

9. Appendix: OLS under simple random sampling

- Scalar regressor: $y_i = \beta x_i + u_i$.
- SRS: (x_i, y_i) i.i.d. with x_i i.i.d. with mean μ_x & u_i i.i.d. with mean 0.
 - ▶ **1.** As $x_i u_i$ are i.i.d. apply Khinchine's Theorem.
Then $N^{-1} \sum_i x_i u_i \xrightarrow{P} E[xu] = E[x] \times E[u] = 0$.
 - ▶ **2.** As x_i^2 are i.i.d. apply Khinchine's Theorem.
Then $N^{-1} \sum_i x_i^2 \xrightarrow{P} E[x^2]$ which we assume exists.
 - ▶ **3.** The probability limit is obtained by combining

$$\begin{aligned}
 \text{plim } \hat{\beta} &= \beta + \text{plim} \left(\frac{\frac{1}{N} \sum_{i=1}^N x_i u_i}{\frac{1}{N} \sum_{i=1}^N x_i^2} \right) \\
 &= \beta + \frac{\text{plim } \frac{1}{N} \sum_{i=1}^N x_i u_i}{\text{plim } \frac{1}{N} \sum_{i=1}^N x_i^2} \\
 &= \beta + \frac{0}{E[x^2]} = \beta,
 \end{aligned}$$

using probability limit continuity ($\text{plim}[a_N/b_N] = a/b$ if $b \neq 0$).

- SRS: assume x_i i.i.d. with mean μ_x and second moment $E[x^2]$ and assume u_i i.i.d. with mean 0 and variance σ^2 .
- Then $x_i u_i$ are i.i.d. with mean $E[xu] = E[x] \times E[u] = 0$, and $V[xu] = E[(xu - 0)^2] = E[x^2 u^2] = E[x^2] E[u^2] = \sigma^2 E[x^2]$.
 - ▶ **1.** Lindeberg-Levy CLT for $N^{-1} \sum_{i=1}^N x_i u_i$ yields

$$\sqrt{N} \left(\frac{N^{-1} \sum_{i=1}^N x_i u_i - 0}{\sqrt{\sigma^2 E[x^2]}} \right) = \frac{\frac{1}{\sqrt{N}} \sum_{i=1}^N x_i u_i}{\sqrt{\sigma^2 E[x^2]}} \xrightarrow{d} \mathcal{N}[0, 1].$$

- ▶ **2.** Convert to $\frac{1}{\sqrt{N}} \sum_{i=1}^N x_i u_i$

$$\frac{1}{\sqrt{N}} \sum_{i=1}^N x_i u_i = \sqrt{\sigma^2 E[x^2]} \times \frac{\frac{1}{\sqrt{N}} \sum_{i=1}^N x_i u_i}{\sqrt{\sigma^2 E[x^2]}}$$

$$\xrightarrow{d} \sqrt{\sigma^2 E[x^2]} \times \mathcal{N}[0, 1]$$

$$\xrightarrow{d} \mathcal{N}[0, \sigma^2 E[x^2]]$$

using product limit normal rule.

- ▶ **3.** The limit distribution is obtained by combining

$$\begin{aligned} \sqrt{N}(\hat{\beta} - \beta) &= \frac{\frac{1}{\sqrt{N}} \sum_{i=1}^N x_i u_i}{\frac{1}{N} \sum_{i=1}^N x_i^2} \\ &\xrightarrow{d} \frac{\mathcal{N}[0, \sigma^2 \mathbf{E}[x^2]]}{\text{plim} \frac{1}{N} \sum_{i=1}^N x_i^2} \\ &\xrightarrow{d} \frac{\mathcal{N}[0, \sigma^2 \mathbf{E}[x^2]]}{\mathbf{E}[x^2]} \\ &\xrightarrow{d} \mathcal{N} \left[0, \sigma^2 (\mathbf{E}[x^2])^{-1} \right] \end{aligned}$$

using $\text{plim} N^{-1} \sum_{i=1}^N x_i^2 = \mathbf{E}[x^2]$ from consistency proof and the product normal limit rule

(or $a_N \times b_N \xrightarrow{d} a \times b$ if $a_N \xrightarrow{d} a$ and $b_N \xrightarrow{p} b$).