

Day 3B

Nonparametrics and Bootstrap

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*Based on A. Colin Cameron and Pravin K. Trivedi (2009,2010),
Microeconometrics using Stata (MUS), Stata Press.
and A. Colin Cameron and Pravin K. Trivedi (2005),
Microeconometrics: Methods and Applications (MMA), C.U.P.*

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1. Introduction

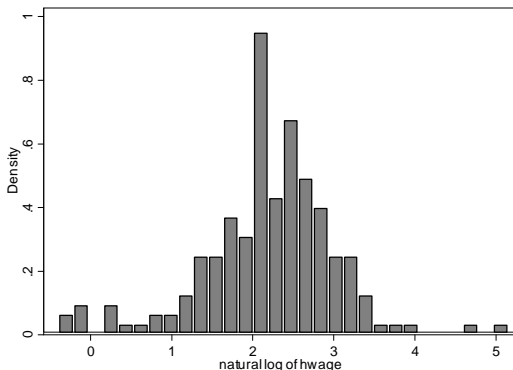
- Brief discussion of nonparametric and semiparametric methods and the bootstrap.
- 1 Introduction
 - 2 Nonparametric (kernel) density estimation
 - 3 Nonparametric (kernel) regression
 - 4 Semiparametric regression
 - 5 Bootstrap
 - 6 Stata Commands
 - 7 Appendix: Histogram and kernel density estimate

2. Nonparametric (kernel) density estimation

- Parametric density estimate
 - ▶ assume a density and use estimated parameters of this density
 - ▶ e.g. normal density estimate: assume $y_i \sim \mathcal{N}[\mu, \sigma^2]$ and use $\mathcal{N}[\bar{y}, s^2]$.
- Nonparametric density estimate: a histogram
 - ▶ break data into bins and use relative frequency within each bin
 - ▶ Problem: a histogram is a step function, even if data are continuous
- Smooth nonparametric density estimate: kernel density estimate.
- Kernel density estimate smooths a histogram in two ways:
 - ▶ use overlapping bins so evaluate at many more points
 - ▶ use bins of greater width with most weight at the middle of the bin.

- Formula: $\hat{f}_{HIST}(x_0) = \frac{1}{2Nh} \sum_{i=1}^N \mathbf{1}(x_0 - h < x_i < x_0 + h)$ or

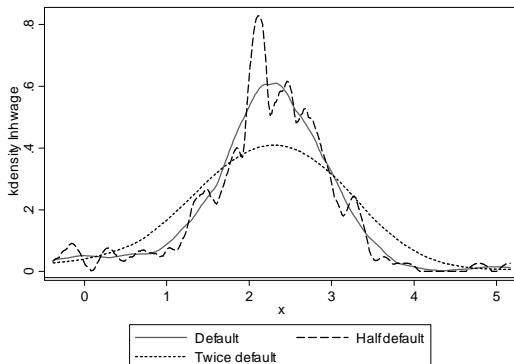
$$\hat{f}_{HIST}(x_0) = \frac{1}{Nh} \sum_{i=1}^N \frac{1}{2} \times \mathbf{1}\left(\left|\frac{x_i - x_0}{h}\right| < 1\right).$$
- Data example: histogram of lnwage for 175 observations
 - ▶ Varies with the bin width (or equivalently the number of bins)
 - ▶ Here 30 bins, each of width $2h \simeq 0.20$ so $h \simeq 0.10$.



- Kernel density estimate of $f(x_0)$ replaces $\mathbf{1}(A)$ by kernel $K(A)$:

$$\hat{f}(x_0) = \frac{1}{Nh} \sum_{i=1}^N K\left(\frac{x_i - x_0}{h}\right)$$

- Data example: kernel of Inwage for 175 observations
 - Epanechnikov kernel $K(z) = 0.75(1 - z^2) \times \mathbf{1}(|z| < 1)$
 - $h = 0.07$ (oversmooths), 0.21 (default) or 0.63 (undersmooths)



Implementation

- Stata examples are
 - ▶ `kdensity y` uses defaults
 - ▶ `kdensity y, bw(0.2)` manually set bandwidth
 - ▶ `kdensity y, normal` overlays the $\mathcal{N}[\bar{y}, s^2]$ density
 - ▶ `hist y, kdensity` gives both histogram and kernel estimates
- Key is choice of bandwidth
 - ▶ The default can oversmooth: may need to decrease `bw()`
- Less important is choice of kernel: default is Epanechnikov.
- Other smooth estimators exist including k-nearest neighbors. But usually no reason to use anything but kernel.

3. Kernel regression: Local average estimator

- The regression model is $y_i = m(x_i) + u_i$, $u_i \sim \text{i.i.d. } (0, \sigma(x_i)^2)$.
 - ▶ The functional form $m(\cdot)$ is not specified, so NLS not possible.
- If many obs have $x = x_0$ use the average of the y_i 's at $x_i = x_0$:

$$\begin{aligned}\hat{m}(x_0) &= \left(\sum_{i: x_i=x_0} y_i \right) / \left(\sum_{i: x_i=x_0} \mathbf{1} \right) \\ &= \left(\sum_{i=1}^N \mathbf{1}(x_i = x_0) y_i \right) / \left(\sum_{i=1}^N \mathbf{1}(x_i = x_0) \right)\end{aligned}$$

- Instead few values of y_i at $x = x_0$ so do local average estimator:

$$\hat{m}(x_0) = \left(\sum_{i=1}^N w_{i0} y_i \right) / \left(\sum_{i=1}^N w_{i0} \right)$$

- ▶ where weights $w_{i0} = w(x_i, x_0)$ are largest for x_i close to x_0 .
- Evaluate at a variety of points x_0 gives regression curve.
- Different methods use different weight functions $w_{i0} = w(x_i, x_0)$

Common nonparametric regression estimators

- 1. Kernel estimate of $m(x_0)$ replaces $\mathbf{1}(x_i - x_0 = 0)$ by $K\left(\frac{x_i - x_0}{h}\right)$

$$\hat{m}(x_0) = \left(\frac{1}{Nh} \sum_{i=1}^N K\left(\frac{x_i - x_0}{h}\right) y_i \right) / \left(\frac{1}{Nh} \sum_{i=1}^N K\left(\frac{x_i - x_0}{h}\right) \right)$$

- 2. Local linear estimate of $\hat{m}(x_0)$ minimizes w.r.t. a_0 and b_0

$$\frac{1}{Nh} \sum_{i=1}^N K\left(\frac{x_i - x_0}{h}\right) (y_i - a_0 - b_0(x_i - x_0))^2$$

- ▶ Motivation: Kernel estimate is equivalent to $\hat{m}(x_0)$ minimizes

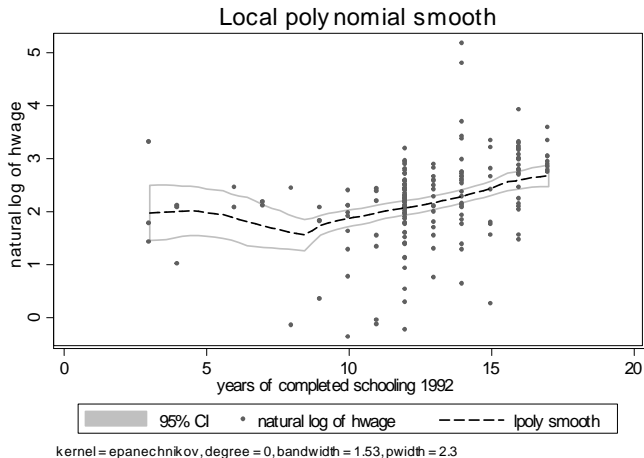
$$\frac{1}{Nh} \sum_{i=1}^N K\left(\frac{x_i - x_0}{h}\right) (y_i - m_0)^2 \text{ with respect to } m_0.$$

- ▶ better on endpoints

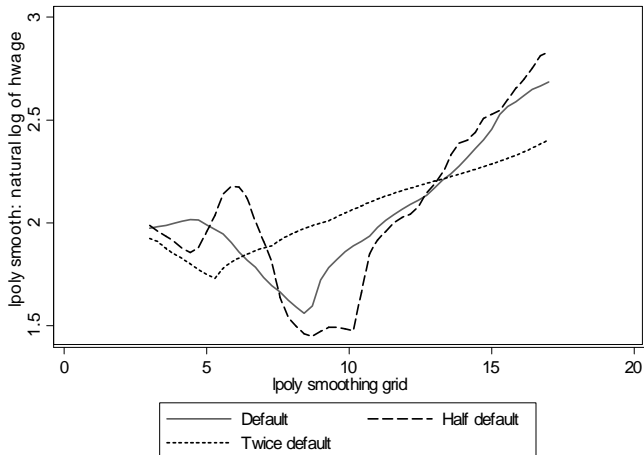
- 3. Lowess (locally weighted scatterplot smoothing)
 - ▶ variation of local linear with variable bandwidth, tricubic kernel and downweighting of outliers.
- 4. K-Nearest neighbors
 - ▶ Average the y_i 's for the k x_i 's that are closest to x_0

- Kernel regression with 95% confidence bands, default Kernel (Epanechnikov) and default bandwidths

▶ `lpoly lnhwage educatn, ci msize(medsmall)`

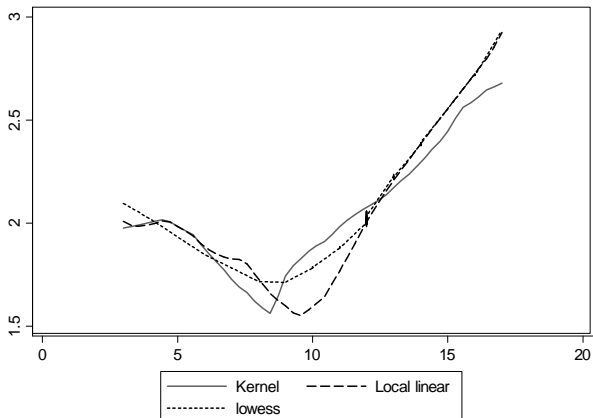


- Kernel regression with three bandwidths: default, half and double.
 - ▶ smoother with larger bandwidth



- Kernel, local linear and lowess with default bandwidths

- ▶ `graph twoway lpoly y x || lpoly y x, deg(1) || lowess y x`
- ▶ kernel erroneously underestimates $m(x)$ at the endpoint $x = 17$.



Implementation

- Different methods work differently
 - ▶ Local linear and local polynomial handle endpoints better than kernel.
- $\hat{m}(x_0)$ is asymptotically normal
 - ▶ this gives confidence bands that allow for heteroskedasticity
- Bandwidth choice is crucial
 - ▶ optimal bandwidth trades off bias (minimized with small bandwidth) and variance (minimized with large bandwidth)
 - ▶ theory just says optimal bandwidth for kernel regression is $O(N^{-0.2})$
 - ▶ “plug-in” or default bandwidth estimates are often not the best
 - ▶ so also try e.g. half and two times the default.
 - ▶ cross validation minimizes the empirical mean square error $\sum_i (y_i - \hat{m}_{-i}(x_i))^2$, where $\hat{m}_{-i}(x_i)$ is the “leave-one-out” estimate of $\hat{m}(x_i)$ formed with y_i excluded.

4. Semiparametric estimation

- Nonparametric regression is problematic when more than one regressor
 - ▶ in theory can do multivariate kernel regression
 - ▶ in practice the local averages are over sparse cells
 - ▶ called the “curse of dimensionality”
- Semiparametric methods place some structure on the problem
 - ▶ parametric component for part of the model
 - ▶ nonparametric component that is often one dimensional

Leading semiparametric examples

- Partially linear model

$$E[y_i | \mathbf{x}_i, \mathbf{z}_i] = \mathbf{x}_i' \boldsymbol{\beta} + \lambda(\mathbf{z}_i)$$

- ▶ Estimate $\lambda(\cdot)$ nonparametrically and ideally $\sqrt{N}(\hat{\boldsymbol{\beta}} - \boldsymbol{\beta}) \xrightarrow{d} \mathcal{N}[\mathbf{0}, \mathbf{V}]$

- Single-index model

$$E[y_i | \mathbf{x}_i] = g(\mathbf{x}_i' \boldsymbol{\beta})$$

- ▶ Estimate $g(\cdot)$ nonparametrically and ideally $\sqrt{N}(\hat{\boldsymbol{\beta}} - \boldsymbol{\beta}) \xrightarrow{d} \mathcal{N}[\mathbf{0}, \mathbf{V}]$
- ▶ Can only estimate $\boldsymbol{\beta}$ up to scale in this model
- ▶ Still useful as ratio of coefficients equals ratio of marginal effects in a single-index models

- Generalized additive model

$$E[y_i | \mathbf{x}_i] = g_1(x_{1i}) + \cdots + g_K(x_{Ki})$$

5. Bootstrap estimate of standard error

- Basic idea is view $\{(y_1, \mathbf{x}_1), \dots, (y_N, \mathbf{x}_N)\}$ as the population.
- Then obtain B random samples from this population
 - ▶ Get B estimates $\hat{\theta}_1, \dots, \hat{\theta}_B$.
 - ▶ Then estimate $\text{Var}[\hat{\theta}]$ using the usual standard deviation of the B estimates

$$\hat{V}[\hat{\theta}] = \frac{1}{B-1} \sum_{b=1}^B (\hat{\theta}_b - \bar{\hat{\theta}})^2, \quad \text{where } \bar{\hat{\theta}} = \frac{1}{B} \sum_{b=1}^B \hat{\theta}_b.$$

- ▶ Square root of this is called a bootstrap standard error.
- To get B different samples of size N we resample with replacement from $\{(y_1, \mathbf{x}_1), \dots, (y_N, \mathbf{x}_N)\}$
 - ▶ In each bootstrap sample some original data points appear more than once while others not appear at all.

Regression application

- Data: Doctor visits (count) and chronic conditions. $N = 50$.

Contains data from bootdata.dta

```
obs:      50
vars:      3                26 Nov 2008 10:46
size:     350
```

variable name	storage type	display format	value label	variable label
docvis	int	%8.0g		number of doctor visits
age	float	%9.0g		Age in years / 10
chronic	byte	%8.0g		= 1 if a chronic condition

Sorted by:

```
. summarize
```

Variable	Obs	Mean	Std. Dev.	Min	Max
docvis	50	4.12	7.82106	0	43
age	50	4.162	1.160382	2.6	6.2
chronic	50	.28	.4535574	0	1

Bootstrap standard errors after Poisson regression

- Use option `vce(boot)`
 - ▶ Set the seed!
 - ▶ Set the number of bootstrap repetitions!

```
. * Compute bootstrap standard errors using option vce(bootstrap) to
. poisson docvis chronic, vce(boot, reps(400) seed(10101) nodots)
```

```
Poisson regression                               Number of obs   =          50
                                                Replications    =          400
                                                wald chi2(1)    =           3.50
                                                Prob > chi2     =          0.0612
                                                Pseudo R2      =          0.0917

Log likelihood = -238.75384
```

	Observed Coef.	Bootstrap Std. Err.	z	P> z	Normal-based [95% Conf. Interval]	
docvis						
chronic	.9833014	.5253149	1.87	0.061	-.0462968	2.0129
_cons	1.031602	.3497212	2.95	0.003	.3461607	1.717042

- Bootstrap se = 0.525 versus White robust se = 0.515.

Results vary with seed and number of reps

```
. * Bootstrap standard errors for different reps and seeds
. quietly poisson docvis chronic, vce(boot, reps(50) seed(10101))

. estimates store boot50

. quietly poisson docvis chronic, vce(boot, reps(50) seed(20202))

. estimates store boot50diff

. quietly poisson docvis chronic, vce(boot, reps(2000) seed(10101))

. estimates store boot2000

. quietly poisson docvis chronic, vce(robust)

. estimates store robust

. estimates table boot50 boot50diff boot2000 robust, b(%8.5f) se(%8.5f)
```

variable	boot50	boot50~f	boot2000	robust
chronic	0.98330	0.98330	0.98330	0.98330
	0.47010	0.50673	0.53479	0.51549
_cons	1.03160	1.03160	1.03160	1.03160
	0.39545	0.32575	0.34885	0.34467

Legend: b/se

Leading uses of bootstrap standard errors

- Sequential two-step m-estimator
 - ▶ First step gives $\hat{\alpha}$ used to create a regressor $z(\hat{\alpha})$
 - ▶ Second step regresses y on x and $z(\hat{\alpha})$
 - ▶ Do a paired bootstrap resampling (x, y, z)
 - ▶ e.g. Heckman two-step estimator.
- 2SLS estimator with heteroskedastic errors (if no White option)
 - ▶ Paired bootstrap gives heteroskedastic robust standard errors.
- Functions of other estimates e.g. $\hat{\theta} = \hat{\alpha} \times \hat{\beta}$
 - ▶ replaces delta method
 - ▶ Clustered data with many small clusters, such as short panels.
 - ★ Then resample the clusters.
 - ★ But be careful if model includes cluster-specific fixed effects.

For these in Stata need to use prefix command `bootstrap`:

The bootstrap: general algorithm

- A general bootstrap algorithm is as follows:
 - ▶ **1.** Given data $\mathbf{w}_1, \dots, \mathbf{w}_N$
 - ★ draw a bootstrap sample of size N (see below)
 - ★ denote this new sample $\mathbf{w}_1^*, \dots, \mathbf{w}_N^*$.
 - ▶ **2.** Calculate an appropriate statistic using the bootstrap sample. Examples include:
 - ★ (a) estimate $\hat{\theta}^*$ of θ ;
 - ★ (b) standard error $s_{\hat{\theta}}^*$ of estimate $\hat{\theta}^*$
 - ★ (c) t -statistic $t^* = (\hat{\theta}^* - \hat{\theta}) / s_{\hat{\theta}}^*$ centered at $\hat{\theta}$.
 - ▶ **3.** Repeat steps 1-2 B independent times.
 - ★ Gives B bootstrap replications of $\hat{\theta}_1^*, \dots, \hat{\theta}_B^*$ or t_1^*, \dots, t_B^* or
 - ▶ **4.** Use these B bootstrap replications to obtain a bootstrapped version of the statistic (see below).

Implementation

- Number of bootstraps: B high is best but increases computer time.
 - ▶ CT use 400 for se's and 999 for tests and confidence intervals.
 - ▶ Defaults are often too low. And set the seed!
- Various resampling methods
 - ▶ 1. Paired (or nonparametric or empirical dist. func.) is most common
 - ★ $\mathbf{w}_1^*, \dots, \mathbf{w}_N^*$ obtained by sampling with replacement from $\mathbf{w}_1, \dots, \mathbf{w}_N$.
 - ▶ 2. Parametric bootstrap for fully parametric models.
 - ★ Suppose $y|\mathbf{x} \sim F(\mathbf{x}, \theta_0)$ and generate y_i^* by draws from $F(\mathbf{x}_i, \hat{\theta})$
 - ▶ 3. Residual bootstrap for regression with additive errors
 - ★ Resample fitted residuals $\hat{u}_1, \dots, \hat{u}_N$ to get $(\hat{u}_1^*, \dots, \hat{u}_N^*)$ and form new $(y_1^*, \mathbf{x}_1), \dots, (y_N^*, \mathbf{x}_N)$.
- Need to resample over i.i.d. observations
 - ▶ resample over clusters if data are clustered
 - ★ But be careful if model includes cluster-specific fixed effects.
 - ▶ resample over moving blocks if data are serially correlated.

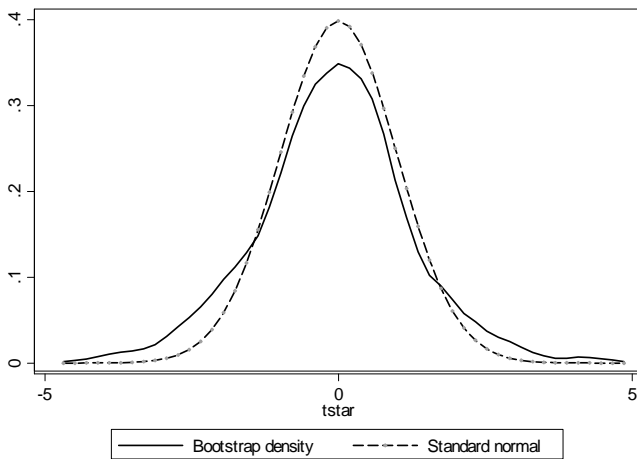
Asymptotic refinement

- The simplest bootstraps are no better than usual asymptotic theory
 - ▶ advantage is easy to implement, e.g. standard errors.
- More complicated bootstraps provide asymptotic refinement
 - ▶ this may provide a better finite-sample approximation.
- Conventional asymptotic tests (such as Wald test).
 - ▶ α = nominal size for a test, e.g. $\alpha = 0.05$.
 - ▶ Actual size = $\alpha + O(N^{-1/2})$.
- Tests with asymptotic refinement
 - ▶ Actual size = $\alpha + O(N^{-1})$.
 - ▶ asymptotic bias of size $O(N^{-1}) < O(N^{-1/2})$ is smaller asymptotically.
 - ▶ But need simulation studies to confirm finite sample gains.
 - ★ e.g. if $N = 100$ then $100/N = O(N^{-1}) > 5/\sqrt{N} = O(N^{-1/2})$.

Asymptotically pivotal statistic

- Asymptotic refinement bootstraps an asymptotically pivotal statistic
 - ▶ this means limit distribution does not depend on unknown parameters.
- An estimator $\hat{\theta} - \theta_0 \stackrel{a}{\sim} \mathcal{N}[0, \sigma_{\hat{\theta}}^2]$ is not asymptotically pivotal
 - ▶ since $\sigma_{\hat{\theta}}^2$ is an unknown parameter.
- But the studentized t -statistic is asymptotically pivotal
 - ▶ since $t = (\hat{\theta} - \theta_0) / s_{\hat{\theta}} \stackrel{a}{\sim} \mathcal{N}[0, 1]$ has no unknown parameters.
- So bootstrap Wald test statistic to get tests and confidence intervals with asymptotically refinement.
- For confidence intervals can also use BC (bias-corrected) and BCa methods.
- Econometricians rarely use asymptotic refinement.

- The solid line bootstrap estimate of the density (with 999 bootstraps) is used to get t-statistic critical values and p values




```
. * Bootstrap confidence intervals: normal-based, percentile, BC, and BCa
. quietly poisson docvis chronic, vce(boot, reps(999) seed(10101) bca)

. estat bootstrap, all
```

```
Poisson regression                Number of obs    =          50
                                Replications      =          999
```

docvis	Observed Coef.	Bias	Bootstrap Std. Err.	[95% Conf. Interval]		
chronic	.98330144	-.0244473	.54040762	-.075878	2.042481	(N)
				-.1316499	2.076792	(P)
				-.0820317	2.100361	(BC)
				-.0215526	2.181476	(BCa)
_cons	1.0316016	-.0503223	.35257252	.3405721	1.722631	(N)
				.2177235	1.598568	(P)
				.2578293	1.649789	(BC)
				.3794897	1.781907	(BCa)

(N) normal confidence interval

(P) percentile confidence interval

(BC) bias-corrected confidence interval

(BCa) bias-corrected and accelerated confidence interval

- (N) is observed coefficient $\pm 1.96 \times$ bootstrap s.e.
- (P) is 2.5 to 97.5 percentile of the bootstrap estimates $\hat{\beta}_1^*, \dots, \hat{\beta}_B^*$.
- (BC) and (BCa) have asymptotic refinement.

Bootstrap failure

- The following are cases where standard bootstraps fail
 - ▶ so need to adjust standard bootstraps.
- GMM (and empirical likelihood) in over-identified models
 - ▶ For overidentified models need to recenter or use empirical likelihood.
- Nonparametric Regression:
 - ▶ Nonparametric density and regression estimators converge at rate less than $\text{root-}N$ and are asymptotically biased.
 - ▶ This complicates inference such as confidence intervals.
- Non-Smooth Estimators: e.g. LAD.

6. Stata commands

- Command `kernel` does kernel density estimate.
- Command `lppoly` does several nonparametric regressions
 - ▶ `kernel` is default
 - ▶ local linear is option `degree(1)`
 - ▶ local polynomial of degree p is option `degree(p)`
- Command `lowess` does Lowess.
- Stata has no built-in commands for the semiparametric estimators
 - ▶ These methods are not easy to automate as no easy way to automate bandwidth choice and treatment of outliers.
- For bootstrap use option `,vce(boot)` or command `bootstrap`:
 - ▶ set the seed!!

7. Appendix: Histogram estimate

- A histogram is a nonparametric estimate of the density of y
 - ▶ break data into bins of width $2h$
 - ▶ form rectangles of area the relative frequency = $freq/N$
 - ▶ the height is $freq/2Nh$ (then area = $(freq/2Nh) \times 2h = freq/N$).
- Use $freq = \sum_{i=1}^N \mathbf{1}(x_0 - h < x_i < x_0 + h)$
 - ▶ where indicator function $\mathbf{1}(\mathbf{A})$ equals 1 if event \mathbf{A} happens and equals 0 otherwise
- The histogram estimate of $f(x_0)$, the density of x evaluated at x_0 , is

$$\begin{aligned} \hat{f}_{HIST}(x_0) &= \frac{1}{2Nh} \sum_{i=1}^N \mathbf{1}(x_0 - h < x_i < x_0 + h) \\ &= \frac{1}{Nh} \sum_{i=1}^N \frac{1}{2} \times \mathbf{1}\left(\left|\frac{x_i - x_0}{h}\right| < 1\right). \end{aligned}$$

Appendix: Kernel density estimate

- Recall $\hat{f}_{HIST}(x_0) = \frac{1}{Nh} \sum_{i=1}^N \frac{1}{2} \times \mathbf{1}(|\frac{x_i - x_0}{h}| < 1)$
- Replace $\mathbf{1}(A)$ by a kernel function
- Kernel density estimate of $f(x_0)$, the density of x evaluated at x_0 , is

$$\hat{f}(x_0) = \frac{1}{Nh} \sum_{i=1}^N K\left(\frac{x_i - x_0}{h}\right)$$

- $K(\cdot)$ is called a kernel function
 - h is called the bandwidth or window width or smoothing parameter h
- Example is Epanechnikov kernel
 - $K(z) = 0.75(1 - z^2) \times \mathbf{1}(|z| < 1)$
 - more weight on data at center. less weight at end
- More generally kernel function must satisfy conditions including
 - Continuous, $K(z) = K(-z)$, $\int K(z) dz = 1$, $\int K(z) dz = 1$, tails go to zero.