

Machine Learning for Microeconometrics

Part 3: Causal Inference with Lasso

A. Colin Cameron
Univ.of California - Davis

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Course Outline

- **1:** Variable selection and cross validation
- **2.** Shrinkage methods
 - ▶ ridge, lasso, elastic net
- **Part 3: ML for causal inference using lasso**
 - ▶ **OLS with many controls, IV with many instruments**
- **4.** Other methods for prediction
 - ▶ nonparametric regression, principal components, splines
 - ▶ neural networks
 - ▶ regression trees, random forests, bagging, boosting
- **5.** More ML for causal inference
 - ▶ ATE with heterogeneous effects and many controls.
- **6.** Classification and unsupervised learning
 - ▶ classification (categorical y) and unsupervised learning (no y).

Introduction

- Consider the leading first work on inference with machine learning.
- This focuses on OLS and IV estimation of the partial linear model
 - ▶ using LASSO to select among potential controls and/or instruments
 - ▶ make assumption of sparsity.
- Work from 2010 on by Belloni, Chernozhukov and Hansen and their coauthors.
- This has been implemented in Stata version 16.

Overview

- 1 Partial linear model
- 2 Partialling-out estimator
- 3 Orthogonalization
- 4 Cross-fit Partialling-out Estimator
- 5 Double Selection Estimator
- 6 Other Models
- 7 Double/debiased machine learning
- 8 References

1.1 Partial Linear Model

- A **partial linear** control function model specifies

$$y = \mathbf{d}'\boldsymbol{\alpha} + g(\mathbf{x}_c) + u \text{ where } g(\cdot) \text{ is unknown.}$$

- Interest lies in estimating $\boldsymbol{\alpha}$
 - ▶ \mathbf{d} are policy or treatment variables of interest
 - ★ for simplicity we will later focus on the scalar case
 - ▶ \mathbf{x}_c are "nuisance" control variables
 - ▶ $g(\cdot)$ is an unknown function
- Selection on observables assumption is made
 - ▶ consistent OLS estimation of $\boldsymbol{\alpha}$ requires $E[u|\mathbf{d}, \mathbf{x}_c] = 0$
 - ▶ this is more plausible the better is $g(\mathbf{x}_c)$.

1.2 Robinson (1988) Semiparametric Estimator

- Robinson (1988) proposed **semiparametric estimation**

$$y = \mathbf{d}'\boldsymbol{\alpha} + g(\mathbf{x}_c) + u, \quad E[u|\mathbf{x}_c] = 0$$

where $g(\cdot)$ is unknown.

- Then

$$\begin{aligned} E[y|\mathbf{x}_c] &= E[\mathbf{d}|\mathbf{x}_c]'\boldsymbol{\alpha} + g(\mathbf{x}_c) + 0 \\ y - E[y|\mathbf{x}_c] &= (d - E[\mathbf{d}|\mathbf{x}_c])'\boldsymbol{\alpha} + u \end{aligned}$$

- Estimate by OLS regression of kernel residuals on kernel residuals

$$u_{y|\mathbf{x}_c} = u_{\mathbf{d}|\mathbf{x}_c}'\boldsymbol{\alpha} + v$$

- ▶ Kernel regression of y on \mathbf{x}_c gives residual $u_{y|\mathbf{x}_c}$
- ▶ Kernel regression of \mathbf{d} on \mathbf{x}_c gives residuals $u_{\mathbf{d}|\mathbf{x}_c}$

- OLS of $u_{y|\mathbf{x}_c}$ on $u_{\mathbf{d}|\mathbf{x}_c}$ gives root- N consistent asymptotically normal $\hat{\boldsymbol{\alpha}}$.

Curse of Dimensionality

- The Robinson method entails kernel regression on a vector \mathbf{x}_c .
- So only works if \mathbf{x}_c is of low dimension
 - ▶ e.g. y = energy consumption; \mathbf{d} = usual demand determinants; \mathbf{x}_c is time of day (scalar).
- Instead we are interested in a high-dimensional set of controls \mathbf{x}_c
 - ▶ kernel regression fails due to the **curse of dimensionality**
 - ★ the sample size required for adequate local regression grows exponentially with the dimension of \mathbf{x}_c .
- Solution: use a machine learner rather than kernel regression
 - ▶ here use the LASSO instead of kernel regression
 - ★ requires a sparsity assumption
 - ★ and use of clever methods.

2.1 Partialling-out estimator

- Allow for complexity by assuming

$$g(\mathbf{x}_c) \simeq \mathbf{x}'\gamma + r$$

where \mathbf{x} consists of flexible transformations of \mathbf{x}_c such as polynomials, interactions, splines, ... and r is an approximation error that disappears at appropriate rate.

- Then

$$y = \mathbf{d}'\alpha + \mathbf{x}'\gamma + r + u.$$

- Belloni, Chernozhukov and coauthors have suggested several LASSO-based methods that yield root- N consistent and asymptotically normal estimates of α
 - ▶ we start with the partialling-out estimator
 - ▶ consider scalar d for simplicity.

2.1 Partialling-out Estimator

- Recall $y = \alpha \times d + \mathbf{x}'\gamma + r + u$.
- Method is similar to Robinson except use LASSO not kernel regression
 - ▶ 1. Perform LASSO of d on \mathbf{x} and obtain residual \hat{u}_d from OLS regression of d on the selected variables.
 - ▶ 2. Perform LASSO of y on \mathbf{x} and obtain residual \hat{u}_y from OLS regression of y on the selected variables.
 - ▶ 3. Obtain $\hat{\alpha}$ from OLS regression of \hat{u}_y on \hat{u}_d .
- **A key assumption is the sparsity assumption** that the true model is small relative to the sample size N and grows at rate no more than \sqrt{N} .
 - ▶ $s/(\sqrt{N}/\ln p)$ should be small
 - ▶ $p = \dim(\mathbf{x})$ is the number of potential regressors
 - ▶ s is the number of variables in the true model.
- Wüthrich and Zhu (2023) find in finite samples Lasso can omit relevant controls leading to omitted variables bias.

2.2 Stata xpo regress command

- `xpo regress depvar varsofinterest, options`
 - ▶ `varsofinterest` is **d**
 - ▶ option `controls([alwaysvars]) othervars` splits **x** into controls to always include and controls to be selected by Stata
 - ▶ default option `plugin` determines the penalty λ by plug-in formula rather than by CV or adaptive CV.
- For independent heteroskedastic errors use the following.
- The plug-in penalty is $\lambda = c\sqrt{N}\Phi(1 - \frac{\gamma}{2p})$
where $c = 1.1$ and $\gamma = 0.1 / \ln\{\max(p, N)\}$.
- LASSO has individual loadings for each regressor
 - ▶ $\kappa_j = \sqrt{\frac{1}{N} \sum_{i=1}^N (x_{ij}\hat{\varepsilon}_i)^2}$ for normalized \mathbf{x}_{ij}
and $\hat{\varepsilon}_i$ is a residual from a sequence of first-stage LASSOs.

2.3. Application of Partialling-out Estimator

- Data is 2003 data from the U.S. Medical Expenditure Panel Survey
 - ▶ people aged 65-90 years.
- Dependent variable `1totexp` is log total medical expenditures.
- Regressor of interest is `suppins`
 - ▶ indicator variable for supplemental insurance beyond Medicare.
- Add many control variables to hopefully control for endogeneity of `suppins`
 - ▶ use LASSO to reduce number of control variables.
- In example here all control variables are chosen by lasso
 - ▶ in practice I would include some variables always such as `totchr`.

Data and key variables

```
. * Data for inference on suppins example: 5 continuous and 13 binary variables
. use mus203mepsmedexp.dta, clear
(A.C.Cameron & P.K.Trivedi (2021): Microeconometrics using Stata, 2e)
```

```
. keep if ltotexp != .
(109 observations deleted)
```

```
. describe ltotexp suppins
```

variable name	storage type	display format	value label	variable label
ltotexp	float	%9.0g		ln(totexp) if totexp > 0
suppins	float	%9.0g		=1 if has supp priv insurance

```
. summarize ltotexp suppins
```

Variable	Obs	Mean	Std. Dev.	Min	Max
ltotexp	2,955	8.059866	1.367592	1.098612	11.74094
suppins	2,955	.5915398	.4916322	0	1

Continuous regressors

```
. * Continuous variables
. global xlist2 income educyr age famsze totchr

. describe $xlist2
```

variable name	storage type	display format	value label	variable label
income	double	%12.0g		annual household income/1000
educyr	double	%12.0g		Years of education
age	double	%12.0g		Age
famsze	double	%12.0g		Size of the family
totchr	double	%12.0g		# of chronic problems

```
. summarize $xlist2
```

Variable	Obs	Mean	Std. Dev.	Min	Max
income	2,955	22.68353	22.60988	-1	312.46
educyr	2,955	11.82809	3.405095	0	17
age	2,955	74.24535	6.375975	65	90
famsze	2,955	1.890694	.9644483	1	13
totchr	2,955	1.808799	1.294613	0	7

Binary regressors

```
. * Discrete binary variables
. global dlist2 female white hisp marry northe mwest south ///
>      msa phylim actlim injury priolist hvvgg

. describe $dlist2
```

variable name	storage type	display format	value label	variable label
female	double	%12.0g	=1 if female	
white	double	%12.0g	=1 if white	
hisp	double	%12.0g	=1 if Hispanic	
marry	double	%12.0g	=1 if married	
northe	double	%12.0g	=1 if northeast area	
mwest	double	%12.0g	=1 if Midwest area	
south	double	%12.0g	=1 if south area (West is excluded)	
msa	double	%12.0g	=1 if metropolitan statistical area	
phylim	double	%12.0g	=1 if has functional limitation	
actlim	double	%12.0g	=1 if has activity limitation	
injury	double	%12.0g	=1 if condition is caused by an accident/injury	
priolist	double	%12.0g	=1 if has medical conditions that are on the priority list	
hvvgg	float	%9.0g	=1 if health status is excellent, good or very good	

OLS without & with products & cross products of controls

- Little change when add all the interactions

```
. * OLS on small model and full model
. global rlist2 c.($xlist2)##c.($xlist2) i.($dlist2) c.($xlist2)#i.($dlist2)

. qui regress ltotexp suppins $xlist2 $dlist2, vce(robust)

. estimates store OLSSMALL

. qui regress ltotexp suppins $rlist2, vce(robust)

. estimates store OLSFULL

. estimates table OLSSMALL OLSFULL, keep(suppins) b(%9.4f) se stats(N df_m r2)
```

Variable	OLSSMALL	OLSFULL
suppins	0.1706 0.0469	0.1868 0.0478
N	2955	2955
df_m	19.0000	99.0000
r2	0.2682	0.3028

Partialling-out Lasso with plug-in lambda

- Estimate between preceding OLS estimates with similar standard error

```
. * Partialling-out partial linear model using default plugin lambda
. poregress ltotexp suppins, controls($rlist2)
```

Estimating lasso for ltotexp using plugin
Estimating lasso for suppins using plugin

```
Partialling-out linear model      Number of obs      =      2,955
                                Number of controls      =      176
                                Number of selected controls =      21
                                Wald chi2(1)              =      15.43
                                Prob > chi2              =      0.0001
```

ltotexp	Coef.	Robust Std. Err.	z	P> z	[95% Conf. Interval]	
suppins	.1839193	.0468223	3.93	0.000	.0921493	.2756892

Note: Chi-squared test is a Wald test of the coefficients of the variables of interest jointly equal to zero. Lassos select controls for model estimation. Type lassoinfo to see number of selected variables in each lasso.

Lassoinfo

- 21 overall, 12 for y and 9 for d
 - ▶ so distinct variables chosen for y and d

```
. * Lasso information
. lassoinfo
```

```
Estimate: active
Command: poregress
```

Variable	Model	Selection method	lambda	No. of selected variables
ltotexp	linear	plugin	.080387	12
suppins	linear	plugin	.080387	9

lassoknots gives the variables chosen

- For y (ltotexp) totchr, actlim, phylim especially important.
- For d (suppins) income especially important.

```
. lassoknots, for(ltotexp)
```

ID	lambda	No. of nonzero In-sample coef. R-squared	Variables (A)dded, (R)emoved, or left (U)nchanged		
* 1	.080387	12 0.2390	A totchr 0.hisp#c.totchr c.educyr#c.totchr 0.actlim#c.famsze	0.actlim 0.hvgg#c.totchr 1.phylim#c.educyr 0.female#c.totchr	c.age#c.totchr 1.white#c.totchr 0.phylim#c.famsze 1.priolist#c.educyr

* lambda selected by plugin assuming heteroskedastic errors.

```
. lassoknots, for(suppins)
```

ID	lambda	No. of nonzero In-sample coef. R-squared	Variables (A)dded, (R)emoved, or left (U)nchanged		
* 1	.080387	9 0.0809	A age 0.hisp#c.educyr 0.marry#c.famsze	income 1.marry#c.income c.income#c.totchr	1.hvgg#c.income 1.white#c.educyr 0.northe#c.income

* lambda selected by plugin assuming heteroskedastic errors.

Partialling out done manually

- The following gives same results as earlier `poregress`

```
. * Partialling out done manually
. qui lasso linear suppins $rlist2, selection(plugin)

. qui predict suppins_lasso, postselection

. qui generate u_suppins = suppins - suppins_lasso

. qui lasso linear ltotexp $rlist2, selection(plugin)

. qui predict ltotexp_lasso, postselection

. qui generate u_ltotexp = ltotexp - ltotexp_lasso

. regress u_ltotexp u_suppins, vce(robust) noconstant noheader
```

	Coef.	Robust Std. Err.	t	P> t	[95% Conf. Interval]	
u_ltotexp						
u_suppins	.1839193	.0468223	3.93	0.000	.0921117	.2757268

Cross validation instead of plugin lambda

- Cross validation selects 73 controls (40 for y and 50 for d).

```
. * Cross validation instead
. poregress ltotexp suppins, controls($rlist2) selection(cv) rseed(10101)
```

Estimating lasso for ltotexp using cv

Estimating lasso for suppins using cv

Partialling-out linear model	Number of obs	=	2,955
	Number of controls	=	176
	Number of selected controls	=	73
	Wald chi2(1)	=	15.58
	Prob > chi2	=	0.0001

ltotexp	Coef.	Robust Std. Err.	z	P> z	[95% Conf. Interval]	
suppins	.1852675	.0469368	3.95	0.000	.0932731	.2772619

Note: Chi-squared test is a Wald test of the coefficients of the variables of interest jointly equal to zero. Lassos select controls for model estimation. Type lassoinfo to see number of selected variables in each lasso.

2.4 Clustered Data

- Data are grouped with correlated observations within group and uncorrelated across groups
 - y_{ig} is outcome for individual i in cluster g , $i = 1, \dots, N_g$, $g = 1, \dots, G$.
- Two methods for the LASSO have objective function

$$\text{Method 1 : } Q_{\lambda}(\boldsymbol{\beta}) = \frac{1}{G} \sum_{g=1}^G \sum_{i=1}^{N_g} (y_{ig} - \mathbf{x}'_{ig} \boldsymbol{\beta})^2 + \lambda \sum_{j=1}^p |\beta_j|$$

$$\text{Method 2 : } Q_{\lambda}(\boldsymbol{\beta}) = \frac{1}{G} \sum_{g=1}^G \frac{1}{N_g} \sum_{i=1}^{N_g} (y_{ig} - \mathbf{x}'_{ig} \boldsymbol{\beta})^2 + \lambda \sum_{j=1}^p |\beta_j|$$

- Stata uses method 2.

Clustered Data (continued)

- Belloni, Chernozhukov, Hansen and Kozbur (2016), “Inference in High-Dimensional Panel Models with an Application to Gun Control”, JBES, 590-606.
- Consider balanced panel model with fixed effects and endogenous regressor
 - ▶ uses partialling out IV given in section 6.2 below
 - ▶ mean difference data (y and \mathbf{x} and possibly \mathbf{z}) to get rid of fixed effects
 - ▶ so now clustered data with fixed effects now eliminated.
- Then consider two uses of machine learning in the partial linear model
 - ▶ section 4.1: select subset of many potential instruments
 - ▶ section 4.2: select subset of many controls.
- They use as method 1. giving equal weight to all mean-differenced observations.

3.1. Orthogonalization defined

- Define α as parameters of interest and η as nuisance parameters.
- Estimate $\hat{\alpha}$ is obtained following first step estimate $\hat{\eta}$ of η
 - ▶ First stage: $\hat{\eta}$ solves $\sum_{i=1}^n \omega(\mathbf{w}_i, \eta) = \mathbf{0}$
 - ▶ Second stage: $\hat{\alpha}$ solves $\sum_{i=1}^n \psi(\mathbf{w}_i, \alpha, \hat{\eta}) = \mathbf{0}$.
- Noise in $\hat{\eta}$ usually affects the distribution $\hat{\alpha}$
 - ▶ e.g. Heckman's two-step estimator in selection models.
- But this is not always the case
 - ▶ e.g. Frisch-Waugh such as mean-differencing out fixed effects.
 - ▶ e.g. the asymptotic distribution of feasible GLS is not affected by first-stage estimation of variance model parameters to get $\hat{\Omega}$.
- Result: The distribution of $\hat{\alpha}$ is unaffected by first-step estimation of η if the function $\psi(\cdot)$ satisfies
 - ▶ $E[\partial \psi(\mathbf{w}_i, \alpha, \eta) / \partial \eta] = \mathbf{0}$; see next slide.
- So choose functions $\psi(\cdot)$ that satisfy the orthogonalization condition

$$E[\partial \psi(\mathbf{w}_i, \alpha, \eta) / \partial \eta] = \mathbf{0}.$$

Orthogonalization (continued)

- Why does this work? By Taylor series expansion

$$\begin{aligned}
 & \frac{1}{\sqrt{n}} \sum_{i=1}^n \psi(\mathbf{w}_i, \hat{\alpha}, \hat{\eta}) \\
 = & \frac{1}{\sqrt{n}} \sum_{i=1}^n \psi(\mathbf{w}_i, \alpha_0, \eta_0) + \frac{1}{n} \sum_{i=1}^n \left. \frac{\partial \psi(\mathbf{w}_i, \alpha, \eta)}{\partial \alpha'} \right|_{\alpha_0, \eta_0} \times \sqrt{n}(\hat{\alpha} - \alpha_0) \\
 & + \frac{1}{n} \sum_{i=1}^n \left. \frac{\partial \psi(\mathbf{w}_i, \alpha, \eta)}{\partial \eta'} \right|_{\alpha_0, \eta_0} \times \sqrt{n}(\hat{\eta} - \eta_0)
 \end{aligned}$$

- By a law of large numbers $\frac{1}{n} \sum_{i=1}^n \left. \frac{\partial \psi(\mathbf{w}_i, \alpha, \eta)}{\partial \eta} \right|_{\alpha_0, \eta_0}$ converges to its expected value which is zero if $E[\partial \psi(\mathbf{w}_i, \alpha, \eta) / \partial \eta] = \mathbf{0}$.
- So the term involving $\hat{\eta}$ drops out.
- For more detail see Cameron and Trivedi (2005, p.201).

3.2 Orthogonalization for partialling-out estimator

- Consider the partially linear model with scalar d and manipulate

$$\begin{aligned}
 y &= \alpha d + g(\mathbf{x}) + u && \text{where } E[u|d, \mathbf{x}] = 0 \\
 \Rightarrow E[y|\mathbf{x}] &= \alpha E[d|\mathbf{x}] + g(\mathbf{x}) && \text{as } E[u|\mathbf{x}] = 0 \\
 y - E[y|\mathbf{x}] &= \alpha(d - E[d|\mathbf{x}]) + u && \text{subtracting}
 \end{aligned}$$

- Robinson (1988) differencing estimator
 - use kernel methods to get $\hat{E}[y|\mathbf{x}]$ and $\hat{E}[d|\mathbf{x}]$
 - $\hat{\alpha}$ from OLS regress $(y - \hat{E}[y|\mathbf{x}])$ on $(d - \hat{E}[d|\mathbf{x}])$
- Instead here use machine learning methods for $\hat{E}[y|\mathbf{x}]$ and $\hat{E}[d|\mathbf{x}]$.
- Recall that OLS of y on \mathbf{x} has f.o.c. $\sum_i \mathbf{x}_i u_i = \mathbf{0}$
 - so is sample analog of population moment condition $E[\mathbf{x}u] = \mathbf{0}$.
- So partialling-out estimator therefore solves population moment condition
 - $E[(d - E[d|\mathbf{x}])\{y - E[y|\mathbf{x}] - (d - E[d|\mathbf{x}])\alpha\}] = 0$.

Orthogonalization for partialling-out estimator (continued)

- Partialling-out solves population condition $E[\psi(\cdot)] = 0$ where

$$\psi(\cdot) = (d - E[d|\mathbf{x}])\{y - E[y|\mathbf{x}] - (d - E[d|\mathbf{x}])\alpha\}.$$

- Define $\eta_1 = E[d|\mathbf{x}]$ and $\eta_2 = E[y|\mathbf{x}]$, so

$$\begin{aligned}\psi(w, \alpha, \boldsymbol{\eta}) &= (d - \eta_1)\{y - \eta_2 - (d - \eta_1)\alpha\} \\ &= (d - \eta_1)(y - \eta_2) - \alpha(d - \eta_1)^2\}.\end{aligned}$$

- Then differentiating

$$\begin{aligned}\partial\psi(\mathbf{w}, \alpha, \boldsymbol{\eta})/\partial\eta_1 &= -(y - \eta_2) + 2\alpha(d - \eta_1) \\ \partial\psi(\mathbf{w}, \alpha, \boldsymbol{\eta})/\partial\eta_2 &= -(d - \eta_1)\end{aligned}$$

- The orthogonalization condition $E[\partial\psi(\mathbf{w}, \alpha, \boldsymbol{\eta})/\partial\boldsymbol{\eta}] = 0$ holds as

$$\begin{aligned}E[-(y - \eta_2) + 2(d - \eta_1)\alpha|\mathbf{x}] &= -(E[y|\mathbf{x}] - \eta_2) + 2\alpha(E[d|\mathbf{x}] - \eta_1) \\ &= -(\eta_2 - \eta_2) + 2\alpha(\eta_1 - \eta_1) = 0 \\ \text{and } E[-(d - \eta_1)|\mathbf{x}] &= -(E[d|\mathbf{x}] - \eta_1) = 0.\end{aligned}$$

Orthogonalization for partialling-out estimator (continued)

- More formally $\eta_{1i} = E[d_{1i}|\mathbf{x}_{1i}]$ and $\eta_{2i} = E[d_{1i}|\mathbf{x}_{1i}]$ vary with i .
- A formal treatment deals with functionals $\eta_{1i} = \eta_1(\mathbf{x}_i)$, $\eta_{2i} = \eta_2(\mathbf{x}_{2i})$
 - ▶ this allows a range of machine learners for d_i and y_i - not just lasso.
- For simplicity consider the linear case where

$$\eta_{1i} = E[d_i|\mathbf{x}] = \mathbf{x}'_i \boldsymbol{\pi}_1 \text{ and } \eta_{2i} = E[y_i|\mathbf{x}] = \mathbf{x}'_i \boldsymbol{\pi}_2$$

- Then

$$\begin{aligned} \psi(w_i, \alpha, \boldsymbol{\pi}) &= (d_i - \mathbf{x}'_i \boldsymbol{\pi}_1) \{y_i - \mathbf{x}'_i \boldsymbol{\pi}_2 - (d_i - \mathbf{x}'_i \boldsymbol{\pi}_1) \alpha\} \\ \partial \psi(w_i, \alpha, \boldsymbol{\pi}) / \partial \boldsymbol{\pi}_2 &= -(d_i - \mathbf{x}'_i \boldsymbol{\pi}_1) \mathbf{x}_i \\ E[\partial \psi(w_i, \alpha, \boldsymbol{\pi}) / \partial \boldsymbol{\pi}_2 | \mathbf{x}_i] &= E[-(d_i - \mathbf{x}'_i \boldsymbol{\pi}_1) \mathbf{x}_i | \mathbf{x}_i] \\ &= -(\mathbf{x}'_i \boldsymbol{\pi}_1 - \mathbf{x}'_i \boldsymbol{\pi}_1) \mathbf{x}_i = \mathbf{0} \end{aligned}$$

- Similarly $E[\partial \psi(w_i, \alpha, \boldsymbol{\pi}) / \partial \boldsymbol{\pi}_1] = 0$.

4.1 Cross-Fit Partialling-Out Estimator

- The preceding partialling out used the same data at the first stage as at the second stage.
- A better procedure uses different data in the first stage lassos to that used for the second stage estimation of α .
- Superficially this leads to a loss of precision in estimating α due to a smaller sample size
 - ▶ this is avoided by the following method.
- Split the sample into K folds and for fold $k = 1, \dots, K$
 - ▶ use most data for LASSO estimation of nuisance part
 - ★ yields model for prediction $\hat{d} = \mathbf{x}'\hat{\pi}_d^{(k)}$ and $\hat{y} = \mathbf{x}'\hat{\pi}_y^{(k)}$
 - ▶ use remaining smaller data to get predicted residuals in fold k
 - ★ compute residuals $\tilde{u}_d^{(k)} = d^{(k)} - \mathbf{x}^{(k)'}\hat{\pi}_d^{(k)}$ and $\tilde{u}_y^{(k)} = y^{(k)} - \mathbf{x}^{(k)'}\hat{\pi}_y^{(k)}$.

Cross-Fit Partialling-Out Estimator (continued)

- Given vectors of residuals $\tilde{u}_d^{(k)}$ and $\tilde{u}_y^{(k)}$ in each of the K folds , $k = 1, \dots, K$ there are two ways to estimate α .
- 1. Combine all residuals into N residuals \tilde{u}_y and \tilde{u}_d , regress and get $\hat{\alpha}$
 - ▶ Stata default
- 2. For each $k = 1, \dots, K$ obtain $\hat{\alpha}^{(k)}$ from OLS of $\tilde{u}_y^{(k)}$ on $\tilde{u}_d^{(k)}$
 - ▶ then form the average $\hat{\alpha} = \frac{1}{K} \sum_{k=1}^K \hat{\alpha}^{(k)}$
 - ▶ there is little loss in efficiency as we average over K independent samples
- Cross-fit partialling out under either method 1. or 2. reduces the complications of data mining
 - ▶ it allows s to grow at rate N and not \sqrt{N} .

4.3 Stata xpo regress command

- `xpo regress depvar varsofinterest, options`
 - ▶ `varsofinterest` is **d**
- Option `controls([alwaysvars]) othervars` splits **x** into controls to always include and controls to be selected by Stata.
- Default option `plugin` determines the penalty λ by plug-in formula rather than by CV or adaptive CV.
 - ▶ default forms N residuals.
- Option `technique(dml1)` computes K estimates $\hat{\alpha}^{(k)'}$ and averages.
- Option `resample(#)` of `xpo regress` uses more than one K -fold split so results not dependent on the random split
 - ▶ should use in final results.

4.4 Cross-fitting partialling-out Application

- Leads to similar results.

```
. * Crossfit partialing out (double/debiased) using default plugin
. xporegress ltotexp suppins, controls($rlist2) rseed(10101) nolog
```

Cross-fit partialing-out	Number of obs	=	2,955
linear model	Number of controls	=	176
	Number of selected controls	=	31
	Number of folds in cross-fit	=	10
	Number of resamples	=	1
	Wald chi2(1)	=	15.66
	Prob > chi2	=	0.0001

ltotexp	Coef.	Robust Std. Err.	z	P> z	[95% Conf. Interval]	
suppins	.1856171	.0469096	3.96	0.000	.093676	.2775582

Note: Chi-squared test is a Wald test of the coefficients of the variables of interest jointly equal to zero. Lassos select controls for model estimation. Type lassoinfo to see number of selected variables in each lasso.

Selected variables across the folds

- Number of selected variables across the ten folds

```
. * Summarize the number of selected variables across the ten folds
. lassoinfo
```

```
Estimate: active
Command: xporegress
```

Variable	Model	Selection method	No. of selected variables		
			min	median	max
ltotexp suppins	linear	plugin	11	13	14
	linear	plugin	7	9	11

4.5 Multiple Sample Splits

- The sample-splitting adds noise.
- To control for this can do the following
 - ▶ S times repeat the sample splitting method (e.g. $S = 500$)
 - ▶ each time get a $\hat{\alpha}_s$ (from averaging the K $\hat{\alpha}'_{ks}$) and $\hat{\sigma}_s^2 = \text{Var}[\hat{\alpha}_s]$
- Then $\bar{\hat{\alpha}} = \frac{1}{S} \sum_{s=1}^S \hat{\alpha}_s$
- And $\text{Var}[\hat{\alpha}] = \frac{1}{S} \sum_{s=1}^S \hat{\sigma}_s^2 + \frac{1}{S} \sum_{s=1}^S (\hat{\alpha}_s - \bar{\hat{\alpha}})^2$.
- This is option `resample(#)` of `xporegress`
 - ▶ should use in final results.

Multiple Splits Application

- This took a long time and the standard error is larger.

```
. xporegress ltotexp suppins, controls($rlist2) rseed(10101) nolog resample(10)
```

```
Cross-fit partialling-out      Number of obs      =      2,955
linear model                   Number of controls    =      176
                               Number of selected controls =      40
                               Number of folds in cross-fit =      10
                               Number of resamples        =      10
                               Wald chi2(1)               =      14.90
                               Prob > chi2               =      0.0001
```

ltotexp	Coef.	Robust Std. Err.	z	P> z	[95% Conf. Interval]	
suppins	.1814719	.0470151	3.86	0.000	.0893239	.2736199

Note: Chi-squared test is a Wald test of the coefficients of the variables of interest jointly equal to zero. Lassos select controls for model estimation. Type lassoinfo to see number of selected variables in each lasso.

5. Double Selection Estimator

- A third method for estimating the partial linear model
 - ▶ used and explained in the Belloni et al 2014 JEP article.
- Recall $y = \alpha \times d + \mathbf{x}'\gamma + r + u$ (where r is approximation error).
- The method is
 - ▶ 1. Perform LASSO of y on \mathbf{x} and denote selected regressor \mathbf{x}_y
 - ▶ 2. Perform LASSO of d on \mathbf{x} and denote selected regressor \mathbf{x}_d .
 - ▶ 3. Obtain $\hat{\alpha}$ from OLS regression of y on d and the union of \mathbf{x}_y and \mathbf{x}_d .
- Use Stata command `dsregress`.

Double Selection Estimator Motivation

- $y = \alpha \times d + \mathbf{x}'\gamma + r + u$
- Naive method 1: LASSO of y on \mathbf{x} where d is always included.
 - ▶ fails as LASSO will not choose variables highly correlated with d since d is already included.
- Naive method 2: LASSO of y on \mathbf{x} and then OLS of y on d and subset of \mathbf{x} chosen by LASSO.
 - ▶ fails as variables omitted by the y on \mathbf{x} LASSO may be ones that are highly correlated with the OLS regressor d .
- Naive method 3: LASSO of d on \mathbf{x} and then OLS of y on d and subset of \mathbf{x} chosen by LASSO.
 - ▶ fails as variables omitted by the d on \mathbf{x} LASSO may be ones that have a large effects in the OLS regression for y .
- There are omitted bias problems.
- The solution is to do naive method 2 and 3 lasso and do OLS on d and the union of the \mathbf{x} 's chosen.

Double Selection Estimator

- Bring in a model for $d = \mathbf{x}'\boldsymbol{\theta} + s + v$ where s is approximation error
- Then $y = \alpha \times (\mathbf{x}'\boldsymbol{\theta} + s + v) + \mathbf{x}'\boldsymbol{\gamma} + r + u = \mathbf{x}'(\alpha\boldsymbol{\theta} + \boldsymbol{\gamma}) + (\alpha s + r) + (u + v) = \mathbf{x}'(\alpha\boldsymbol{\theta} + \boldsymbol{\gamma}) + t + w$
- We have

$$y_i = \mathbf{x}_i'\boldsymbol{\theta} + t_i + w_i$$

$$d_i = \mathbf{x}_i'\boldsymbol{\theta} + s_i + v_i$$

- The double selection procedure implicitly obtains estimates of w_i and v_i and obtains $\hat{\alpha}$ by regressing the estimates of w_i on the estimates of v_i .
 - ▶ this is implicitly Robinson (1988).

Double Selection Estimator Application

- Double selection yields similar results to before.

```
. * Double selection partial linear model using default plugin lambda
. dsregress ltotexp suppins, controls($rlist2)
```

```
Estimating lasso for ltotexp using plugin
Estimating lasso for suppins using plugin
```

```
Double-selection linear model      Number of obs      =      2,955
                                Number of controls        =      176
                                Number of selected controls =      21
                                Wald chi2(1)                =     15.30
                                Prob > chi2                 =     0.0001
```

ltotexp	Coef.	Robust Std. Err.	z	P> z	[95% Conf. Interval]	
suppins	.1836224	.0469429	3.91	0.000	.091616	.2756289

Note: Chi-squared test is a Wald test of the coefficients of the variables of interest jointly equal to zero. Lassos select controls for model estimation. Type lassoinfo to see number of selected variables in each lasso.

6.1 Generalized Linear Models

- In economics we extend from OLS using the GMM framework
 - ▶ this handles both nonlinearity and endogeneity.
- In statistics the main extension is to commonly-used nonlinear models
 - ▶ **generalized linear models** (GLM) for independent data
 - ▶ generalized estimating equations (GEE) for clustered and panel data.
- A generalized linear model specifies $E[y|\mathbf{x}] = G(\mathbf{x}'\boldsymbol{\beta})$ for specified $G(\cdot)$
- The GLM literature calls the $G^{-1}(\cdot)$ the link function
 - ▶ $G(a) = a$ for linear model uses the identity or linear link
 - ▶ $G(a) = \exp(a)$ for Poisson for count y uses the log link since $G^{-1}(a) = \ln a$.
 - ▶ $G(a) = \Lambda(a) = \frac{e^a}{1+e^a}$ for logit for binary y .

Generalized Linear Models (continued)

- Estimators for GLMs are quasi-MLEs based on the linear exponential family which includes
 - normal distribution (with σ^2 known)
 - Bernoulli and binomial (with number of trials known)
 - Poisson
 - exponential.
- For these models when the "canonical" link is used (which is $G(a) = a$ for normal, $G(a) = \exp(a)$ for Poisson and
 - $G(a) = \Lambda(a) = \frac{e^a}{1+e^a}$ for Bernoulli the resulting estimating equations are

$$\begin{aligned}\sum_{i=1}^n \{y_i - G(\mathbf{x}_i' \boldsymbol{\beta})\} \mathbf{x}_i &= \mathbf{0} \\ \sum_{i=1}^n \text{residual}_i \times \text{regressors}_i &= \mathbf{0}.\end{aligned}$$

- Then consistency of $\hat{\boldsymbol{\beta}}$ only requires correct specification of the mean, since $E[y_i - G(\mathbf{x}_i' \boldsymbol{\beta})] \mathbf{x}_i = \mathbf{0}$ if $E[y_i | \mathbf{x}_i] = G(\mathbf{x}_i' \boldsymbol{\beta})$.
 - The GLM quasi-MLEs have similar robustness properties to OLS.

Causal Inference for Partial Linear GLM

- Now consider a **partial linear GLM**

- ▶ a generalization of partial linear $E[y|\mathbf{x}] = \alpha d + g(\mathbf{x}_c)$.

- The problem is that the function $g(\cdot)$ is unspecified in

$$E[y|\mathbf{x}] = G(\alpha d + g(\mathbf{x}_c)) \text{ for specified } G(\cdot).$$

- We will again want to approximate $g(\mathbf{x}_c) \simeq \mathbf{x}'_c \boldsymbol{\beta}$.
- The paper Belloni, Chernozhukov and Wei (2016), JBES, 606-609, proposes two methods
 - ▶ 1. Estimator based on optimal instrument (Table 1)
 - ★ Stata perhaps misleadingly calls this "partialling-out"
 - ▶ 2. Estimator based on double selection (Table 2).
- Both estimators are complicated - see the paper or Stata documentation.

Optimal instrument approach

- We have the unconditional moment condition (given $g(\mathbf{x}_c) \simeq \mathbf{x}'\boldsymbol{\beta}$)

$$E[\{y_i - G(\alpha d_i + \mathbf{x}'_i \boldsymbol{\beta})\} | d_i, \mathbf{x}_i] = 0$$

- It follows that for any function $f(d_i, \mathbf{x}_i)$ unconditionally

$$E[\{y_i - G(\alpha d_i + \mathbf{x}'_i \boldsymbol{\beta})\} \times f(d_i, \mathbf{x}_i)] = 0.$$

- If $\boldsymbol{\beta}$ were known then we could estimate the scalar α as solving the single equation

$$\sum_{i=1}^n \{y_i - G(\alpha d_i + \mathbf{x}'_i \boldsymbol{\beta})\} z_i = 0$$

for some scalar “instrument” $z_i = f(d_i, \mathbf{x}_i)$.

- We instead first estimate $\tilde{\boldsymbol{\beta}}$, so the estimating equation for α is then

$$\sum_{i=1}^n \psi(\mathbf{w}_i, \alpha, \tilde{\boldsymbol{\beta}}) = \sum_{i=1}^n \{y_i - G(\alpha d_i + \mathbf{x}'_i \tilde{\boldsymbol{\beta}})\} z_i = 0.$$

Causal Inference for Partial Linear GLM (continued)

- The estimating equation for α is

$$\sum_{i=1}^n \psi(\mathbf{w}_i, \alpha, \tilde{\boldsymbol{\beta}}) = \sum_{i=1}^n \{y_i - G(\alpha d_i + \mathbf{x}_i' \tilde{\boldsymbol{\beta}})\} z_i = 0.$$

- The partialling-out GLM estimator does the following
 - ▶ 1. Post-lasso logit or Poisson of y_i on d_i and \mathbf{x}_i gives first-stage $\tilde{\alpha}$ and $\tilde{\boldsymbol{\beta}}$.
 - ▶ 2. Construct an “instrument” z_i for d_i based on $\tilde{\alpha}$ and $\tilde{\boldsymbol{\beta}}$
 - ★ this is the tricky bit - see next slide
 - ▶ 3. Estimator α solves the preceding sample moment condition.

Causal Inference for Partial Linear GLM (continued)

- The population moment condition is

$$E[\psi(\mathbf{w}, \alpha, \beta)] = E[\{y - G(\alpha d + \mathbf{x}'\beta)\} \times z] = 0.$$

- The hard part is constructing the “instrument” z from the \mathbf{x}' s and $\tilde{\alpha}$ and $\tilde{\beta}$

- ▶ (1) the instrument is relevant

$$E\left[\frac{\psi(\mathbf{w}, \alpha, \beta)}{\partial \alpha}\right] = E[\{y - G(\alpha d + \mathbf{x}'\beta)\} \times G'(\alpha d + \mathbf{x}'\beta) \times d \times z] \neq 0$$

- ▶ (2) the instrument is such that the orthogonalization condition holds

$$E\left[\frac{\psi(\mathbf{w}, \alpha, \beta)}{\partial \beta}\right] = E[\{y - G(\alpha d + \mathbf{x}'\beta)\} \times G'(\alpha d + \mathbf{x}'\beta) \times \mathbf{x} \times z] = \mathbf{0}.$$

- ▶ (3) For more precise estimation an “efficient” instrument is chosen.
- For details see Stata documentation and Belloni, Chernozhukov and Wei (2016), JBES, 606-609.

Partial Linear Logit Model

- Here $\Pr[y = 1|d, \mathbf{x}] = \Lambda(\alpha \times d + \mathbf{x}'\boldsymbol{\beta})$ and we want to select \mathbf{x} .
- Logit commands are `pologit`, `xpologit` and `dslogit`.
- Marginal effects are not identified as they depend on $\boldsymbol{\beta}$ and here we have only consistently estimated α

$$\frac{\partial}{\partial d} \Lambda(\alpha \times d + \mathbf{x}'\boldsymbol{\beta}) = \alpha \times \Lambda'(\alpha \times d + \mathbf{x}'\boldsymbol{\beta}).$$

- But logit coefficients have an odds ratio interpretation, since

$$\begin{aligned} \text{for logit model } \frac{p}{1-p} &= \exp(\alpha \times d + \mathbf{x}'\boldsymbol{\beta}) \\ \text{and } \frac{\partial}{\partial d} \exp(\alpha \times d + \mathbf{x}'\boldsymbol{\beta}) &= \alpha \times \exp(\alpha \times d + \mathbf{x}'\boldsymbol{\beta}). \end{aligned}$$

- Example: $\alpha = 0.2$ then a one unit change in d increases the odds ratio by a multiple $e^{0.2} = 1.22$.

Logit Model Application

- Define a binary outcome dy for whether or not $totexp > 4000$
 - then $dy=1$ for 42% of sample and $dy=0$ for 58%
 - so odds at \bar{y} is $\bar{y}/(1 - \bar{y}) = 0.72$.
 - here do both partialling-out and double selection

```

. * Logit variant of partial linear model and partialing-out estimator
. generate dy = totexp > 4000

. qui logit dy suppins $rlist2, or vce(robust)

. estimates store FULL

. qui pologit dy suppins, controls($rlist2) selection(plugin) coef

. estimates store PARTIAOUT

. qui dslogit dy suppins, controls($rlist2) coef

. estimates store DOUBSEL

. estimates table FULL PARTIAOUT DOUBSEL, keep(suppins) b(%9.4f) se ///
>      stats(N df_m k_controls_sel)

```

Variable	FULL	PARTIAL~T	DOUBSEL
suppins	0.2792 0.0936	0.2632 0.0892	0.2680 0.0892
N	2955	2955	2955
df_m	99.0000		
k_controls~l		19.0000	19.0000

legend: b/se

Exponential Conditional Mean Partial Linear Model (Poisson)

- Note that Poisson regression is applicable to any model with exponential conditional mean
 - ▶ it is not restricted to counts or Poisson
 - ▶ but do be sure to use robust standard errors.
- Here $E[y|d, \mathbf{x}] = \exp(\alpha \times d + \mathbf{x}'\boldsymbol{\beta})$ and we want to select \mathbf{x} .
- Poisson commands are `popoisson`, `xpopoisson` and `dspoisson`.
- Marginal effects are not identified as they depend on $\boldsymbol{\beta}$ and here we have only estimated α

$$\frac{\partial}{\partial d} \exp(\alpha \times d + \mathbf{x}'\boldsymbol{\beta}) = \alpha \times \exp(\alpha \times d + \mathbf{x}'\boldsymbol{\beta}).$$

- But exponential coefficients have a semi-elasticity or multiplicative interpretation.
- Example: $\alpha = 0.2$ then a one unit change in d increases the conditional mean by a multiple 0.2.

6.2 Linear Instrumental Variables

- Consider a partial linear model with a single endogenous regressor
 - ▶ estimation is by instrumental variables (IV).
- Problem 1: If we have hat if we add too many controls then we are more likely to have a weak instrument as the instrument has less incremental contribution after controlling for the exogenous variables.
- Problem 2: If we have too many instruments we again run into weak instrument problem.
- Solution is to extend earlier partialling-out to restrict number of controls and/or number of controls.
- The `poivregress` command applies to multiple endogenous regressors (**d**), regressors to always include (**w**) and controls to reduce (**x**). There are instruments **z** with $\dim[\mathbf{z}] \geq \dim[\mathbf{x}]$.

$$y = \mathbf{d}'\alpha + \mathbf{w}'\delta + \mathbf{x}'\gamma + u.$$

Partialling-out for Linear Instrumental Variables

- Consider scalar endogenous regressor d , potential exogenous regressors \mathbf{x} , additional instruments \mathbf{z} , and, for simplicity, no exogenous variables to definitely include ($\delta = \mathbf{0}$):

$$y = \alpha \times d + \mathbf{x}'\gamma + u.$$

- The partialling-out method is

- Calculate a partial-out independent variable \hat{u}_y
 - perform LASSO of y on \mathbf{x} and obtain residual \hat{u}_y from OLS regression of y on the selected variables.
- Calculate a scalar instrument \tilde{u}_d as follows
 - perform LASSO of d on \mathbf{x} and \mathbf{z} obtain prediction \hat{d} from OLS of d on the selected variables
 - perform LASSO of \hat{d} on \mathbf{x} and obtain prediction \tilde{d} and residual \tilde{u}_d from OLS of \hat{d} on the selected variables
- Calculate a partialled-out endogenous regressor
 - $\hat{u}_d = d - \tilde{d}$ which has purged out the role of \mathbf{x} .
- Obtain $\hat{\alpha}$ from IV regression of \hat{u}_y on \hat{u}_d with instrument \tilde{u}_d .

Partialling-out IV Application

- Just-identified example from Acemoglu, Johnson and Robinson (2001), AER, 1369-1401
- Consider country GDP and role of secure institutions
 - ▶ y : loggdp (log PPP GDP per capita in 1995, World Bank)
 - ▶ d : avexpr (average protection against expropriation risk)
 - ▶ z : logem4 (log settler mortality - a long time ago)
 - ▶ x : measures of country latitude, temperature, humidity, soil types and natural resources.
- Problem: 24 potential controls and $n = 64$.

Data summary

- From output not given $\text{Cor}(d, z) = \text{Cor}[\text{avexpr}, \text{logem4}] = -0.52$.

```
. * Read in Acemoglu-Johnson-Robinson data and define globals
. qui use mus228ajr.dta, clear

. global xlist lat_abst edes1975 avelf temp* humid* steplow deslow ///
>    stepmid desmid drystep drywint goldm iron silv zinc oilres landlock

. describe logpgp95 avexpr logem4
```

variable name	storage type	display format	value label	variable label
logpgp95	float	%9.0g		log PPP GDP pc in 1995, World Bank
avexpr	float	%9.0g		average protection against expropriation risk
logem4	float	%9.0g		log settler mortality

```
. summarize logpgp95 avexpr logem4, sep(0)
```

Variable	Obs	Mean	Std. Dev.	Min	Max
logpgp95	64	8.062237	1.043359	6.109248	10.21574
avexpr	64	6.515625	1.468647	3.5	10
logem4	64	4.657031	1.257984	2.145931	7.986165

poivregress results

- Across the various Lassos **five control variables are selected**.

```
. * Partialling-out IV using plugin for lambda
. poivregress logpgp95 (avexpr=logem4), controls($xlist) selection(plugin, hom)
```

Estimating lasso for logpgp95 using plugin

Estimating lasso for avexpr using plugin

Estimating lasso for pred(avexpr) using plugin

```
Partialling-out IV linear model      Number of obs      =          64
                                     Number of controls   =          24
                                     Number of instruments =           1
                                     Number of selected controls =           5
                                     Number of selected instruments =           1
                                     Wald chi2(1)            =          8.74
                                     Prob > chi2            =          0.0031
```

logpgp95	Coef.	Robust Std. Err.	z	P> z	[95% Conf. Interval]	
avexpr	.8798503	.2976286	2.96	0.003	.296509	1.463192

Endogenous: avexpr

Note: Chi-squared test is a Wald test of the coefficients of the variables of interest jointly equal to zero. Lassos select controls for model estimation. Type lassoinfo to see number of selected variables in each lasso.

6.3 Belloni, Chernozhukov and Hansen (JEP, 2014)

- Belloni, Chernozhukov and Hansen (2014), “High-dimensional methods and inference on structural and treatment effects,” *Journal of Economic Perspectives*, Spring, 29-50
- Accessible paper. Three applications using LASSO.
- 1. IV with excess of instruments and use LASSO to select subset.
 - ▶ Application to house prices (y) affected by takings law (d) with 147 potential instruments and $n = 184$. Lasso picked just one instrument.
- 2. OLS with excess of controls and use double selection method.
 - ▶ Application to crime rate (y) affected by abortion rate (d) with 284 controls and $n = 550$. Around 10 controls are selected.
- 3. Just-identified IV with single y , d and z . Three LASSOs of y , x and z on \mathbf{x} and then use the union of the chosen \mathbf{x} 's as controls in IV of y on d with instrument d .
 - ▶ so like double selection rather than partialling-out IV of `poivregress`.
 - ▶ Application same as the Acemoglu et al. example in these slides.

7.1 Double or Debiased Machine Learning

- Chernozhukov, Chetverikov, Demirer, Duflo, Hansen, Newey and Robins (2018), “Double/debiased machine learning for treatment and structural parameters,” *The Econometrics Journal*.
- Interest lies in estimation of key parameter(s) controlling for high-dimensional nuisance parameters.
- Two components to double ML or debiased ML and subsequent inference
 - ▶ Work with orthogonalized moment conditions to allow consistent estimation of parameter(s) of interest
 - ★ Chernozhukov et al. call this Neyman orthogonalization as the Neyman (1959, 1979) c-alpha test in the likelihood framework uses orthogonalization
 - ★ see section 3 of Chernozhukov, Hansen and Martin Spindler (2015), *Annual Review of Economics* for details and how to obtain an orthogonalized moment condition.
 - ▶ Use sample splitting (cross fitting) to remove bias induced by overfitting.

Double or Debiased Machine Learning (continued)

- Then get asymptotic normal confidence intervals for parameters of interest
 - ▶ where a variety of ML methods can be used
 - ★ random forests, lasso, ridge, deep neural nets, boosted trees, ensembles
 - ▶ that don't necessarily need sparsity
 - ▶ and theory does not require Donsker properties.
- Can apply to
 - ▶ partial linear model (with exogenous or endogenous regressor)
 - ★ done in these slides using LASSO
 - ▶ ATE and ATET under unconfoundedness
 - ★ will be covered in part 5
 - ▶ LATE in an IV setting.
- Stata addon and R package ddml due to Ahrens, Hansen, Schaffer and Wiemann (2024) covers a range of models and machine learners.

7.2 Caution

- The LASSO methods are easy to estimate using Stata 16
 - ▶ they'll be (blindly) used a lot.
- However in any application
 - ▶ is the underlying assumption of sparsity reasonable?
 - ▶ has the asymptotic theory kicked in?
 - ▶ are the default values of c and γ reasonable?
 - ▶ are model assumptions such as instrument validity reasonable?
- Wüthrich and Zhu (2021) find that the lasso methods can fail to pick up all relevant control variables leading to considerable omitted variables bias
 - ▶ an alternative is to include all potential regressors directly and use recently developed methods for inference with many controls.

8. References

- Chapter 28.8 “Machine Learning for prediction and inference” in A. Colin Cameron and Pravin K. Trivedi (2022), *Microeconometrics using Stata*, Second edition, forthcoming.
- Belloni, Chernozhukov and Hansen and coauthors have many papers
 - ▶ focus on the following papers.
- Belloni, Chernozhukov and Hansen (2014), “High-dimensional methods and inference on structural and treatment effects,” *Journal of Economic Perspectives*, Spring, 29-50
 - ▶ accessible paper with three applications.
- Ahrens, Hansen and Schaffer (2020), “lassopack: Model selection and prediction with regularized regression in Stata,” *Stata Journal*, 176-235 (also ArXiv:1901.05397).
 - ▶ more detail on LASSO methods as well as on Stata add-on commands
 - ▶ generally supplanted by Stata version 16 commands but does some things not in Stata 16.

References (continued)

- Belloni, Chernozhukov and Hansen (2011), “Inference Methods for High-Dimensional Sparse Econometric Models,” Advances in Economics and Econometrics, ES World Congress 2010, ArXiv 2011
 - ▶ even more detail and summarizes several of their subsequently published papers.
- Alex Belloni, D. Chen, Victor Chernozhukov and Ying Wei (2016), “Post-Selection Inference for Generalized Linear Models With Many Controls,” JBES, 34(4), 606-619.
- Alex Belloni, D. Chen, Victor Chernozhukov and Christian Hansen (2012), “Sparse Models and Methods for Optimal Instruments with an Application to Eminent Domain”, Econometrica, Vol. 80, 2369-2429.
 - ▶ IV application.
- Victor Chernozhukov, Denis Chetverikov, Mert Demirer, Esther Duflo, Christian Hansen, Whitney Newey and James Robins (2018), “Double/debiased machine learning for treatment and structural parameters,” The Econometrics Journal, 21, C1-C68.

References (continued)

- Ahrens, Hansen, Schaffer and Wiemann (2024), "ddml: Double/debiased Machine Learning in Stata," Stata Journal, 3-45.
- Victor Chernozhukov, Christian Hansen, and Martin Spindler (2015), "Valid Post-Selection and Post-Regularization Inference: An Elementary, General Approach," Annual Review of Economics, 649-688.
- Kaspar Wüthrich and Ying Zhu (2023), "Omitted variable bias of Lasso-based Inference Methods: A finite sample analysis," Review of Econ and Stat, 982-997.
- Matias Cattaneo, Michael Jansson and Whitney Newey (2018), "Inference in Linear Regression Models with Many Covariates and Heteroskedasticity," JASA, 113(523), 1350-1361.
- Maryam Feyzollahi and Nima Rafizadeh (2024), "Double/Debiased Machine Learning for Economists: Practical Guidelines, Best Practices, and Common Pitfalls," https://papers.ssrn.com/sol3/papers.cfm?abstract_id=4703243